Lecture 19:

Eigenvalues and eigenvectors Diagonalizability Characteristic polynomial Eigenspaces

### Warmup

1. Compute the determinants of

$$X = \begin{pmatrix} 10 & -9 \\ 4 & -2 \end{pmatrix}, \quad Y = \begin{pmatrix} -2 & -1 \\ 5 & 2 \end{pmatrix}, \text{ and } Z = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 0 & -2 \\ -1 & 2 & 3 \end{pmatrix}.$$

2. Let  $\lambda \in F$ . Compute the determinants of

$$X = \begin{pmatrix} 10 - \lambda & -9 \\ 4 & -2 - \lambda \end{pmatrix}, \quad Y = \begin{pmatrix} -2 - \lambda & -1 \\ 5 & 2 - \lambda \end{pmatrix},$$
  
and 
$$Z = \begin{pmatrix} 1 - \lambda & 2 & 1 \\ 2 & -\lambda & -2 \\ -1 & 2 & 3 - \lambda \end{pmatrix}.$$

[Your answers should be in terms of  $\lambda$ . Reality check: evaluate your answers here  $\lambda = 0$ , and compare to your answers to 1. ]

Answers to warmup:

1. det 
$$\begin{pmatrix} 10 & -9 \\ 4 & -2 \end{pmatrix} = 10(-2) - (-9)4 = 16;$$
  
det  $\begin{pmatrix} -2 & -1 \\ 5 & 2 \end{pmatrix} = (-2)(2) - (-1)(5) = 1;$  and  
det  $\begin{pmatrix} 1 & 2 & 1 \\ 2 & 0 & -2 \\ -1 & 2 & 3 \end{pmatrix} = (-1)^{2+1}(2) \det \begin{pmatrix} 2 & 1 \\ 2 & 3 \end{pmatrix} + (-1)^{2+2}(0) \det \begin{pmatrix} 1 & 1 \\ -1 & 3 \end{pmatrix}$   
 $+ (-1)^{2+3}(-2) \det \begin{pmatrix} 1 & 2 \\ -1 & 2 \end{pmatrix}$  (expanding along row 2)  
 $= -2((2)(3) - (1)(2)) + 0 - (-2)((1)(2) - (2)(-1)) = 0.$   
2. det  $\begin{pmatrix} 10 - \lambda & -9 \\ 4 & -2 - \lambda \end{pmatrix} = (10 - \lambda)(-2 - \lambda) - (-9)4 = \lambda^2 - 8\lambda + 16;$   
det  $\begin{pmatrix} -2 - \lambda & -1 \\ 5 & 2 - \lambda \end{pmatrix} = (-2 - \lambda)(2 - \lambda) - (-1)(5) = \lambda^2 + 1;$  and  
det  $\begin{pmatrix} 1 - \lambda & 2 & 1 \\ 2 & -\lambda & -2 \\ -1 & 2 & 3 - \lambda \end{pmatrix}$  (expanding along row 1)  
 $= (-1)^{1+1}(1 - \lambda) \det \begin{pmatrix} -\lambda & -2 \\ 2 & 3 - \lambda \end{pmatrix} + (-1)^{1+2}(2) \det \begin{pmatrix} 2 & -2 \\ -1 & 3 - \lambda \end{pmatrix} + (-1)^{1+3}(1) \det \begin{pmatrix} 2 & -\lambda \\ -1 & 2 \end{pmatrix}$   
 $= (1 - \lambda)(-\lambda(3 - \lambda) - (-2)(2)) - 2(2(3 - \lambda) - (-1)(-2)) + (2(2) - (-\lambda)(-1)))$   
 $= -\lambda^3 + 4\lambda^2 - 4\lambda.$ 

# Eigenvectors and eigenvalues

Let V be a f.d. vector space over a field F, and let  $f: V \to V$  be an endomorphism (linear). An **eigenvector** for f is a vector  $\mathbf{v} \in V$  such that f only scales  $\mathbf{v}$  (the direction doesn't change):

$$f(\mathbf{v}) = \lambda \mathbf{v}, \quad \text{for some } \lambda \in F.$$

If  $\mathbf{v} \neq \mathbf{0}$ , then we call  $\lambda$  an **eigenvalue** for f.

[Root: eigen is a German word meaning "belonging to" or "inherent to".] Similarly, for any matrix  $X \in M_n(F)$ , eigenvectors and eigenvalues of X are the same as eigenvectors and eigenvalues of the associated endomorphism on  $F^n$  (with respect to the standard ordered basis).

**Example.** For any  $X \in M_n(F)$  and any  $\lambda \in F$ , we have  $X\mathbf{0} = \mathbf{0} = \lambda \mathbf{0}$ .

So **0** is an eigenvector of any matrix. But this is exactly why we require that there's some *nonzero* **v** satisfying X**v** =  $\lambda$ **v** to call  $\lambda$  an eigenvalue of X.

(We want being an eigenvalue to be special.)

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Example. Let

$$X = \begin{pmatrix} -1 & 2 \\ -6 & 6 \end{pmatrix}, \quad \mathbf{u} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}, \quad \text{and} \quad \mathbf{v} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

Then

$$X\mathbf{u} = \begin{pmatrix} -1 & 2\\ -6 & 6 \end{pmatrix} \begin{pmatrix} 2\\ 3 \end{pmatrix} = \begin{pmatrix} 4\\ 6 \end{pmatrix} = \mathbf{2} \begin{pmatrix} 2\\ 3 \end{pmatrix} = \mathbf{2u};$$

and

$$X\mathbf{v} = \begin{pmatrix} -1 & 2\\ -6 & 6 \end{pmatrix} \begin{pmatrix} 1\\ 2 \end{pmatrix} = \begin{pmatrix} 3\\ 6 \end{pmatrix} = \mathbf{3} \begin{pmatrix} 1\\ 2 \end{pmatrix} = \mathbf{3v}.$$

So 2 and 3 are eigenvalues of X, and  $\mathbf{u}$  and  $\mathbf{v}$  are eigenvectors of X (of eigenvalue 2 and 3, respectively).

Notice:  $\mathcal{B} = \left\langle \begin{pmatrix} 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix} \right\rangle$  is a basis of  $F^2$ . And with respect to this basis, the above calculations show

$$\operatorname{Rep}_{\mathcal{B}}^{\mathcal{B}}(f_X) = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix},$$

where  $f_X: F^2 \to F^2$  is the linear function associated to X. In particular,

$$X = PDP^{-1}$$
 where  $D = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$  and  $P = \begin{pmatrix} 2 & 1 \\ 3 & 2 \end{pmatrix}$ 

Why is this great? For example, what if we wanted to compute  $X^{100}$ ?

**Theorem.** Let  $X \in M_n(F)$  with corresponding linear function  $f_X : F^n \to F^n$ . Suppose  $\mathcal{B} = \langle \mathbf{v}_1, \dots, \mathbf{v}_n \rangle$  is an ordered basis of eigenvectors with corresponding eigenvalues  $\lambda_1, \dots, \lambda_n$ , i.e.,

$$X\mathbf{v}_i = \lambda_i \mathbf{v}_i$$
 for  $i = 1, \dots, n$ 

Let P be the matrix whose columns are  $\mathbf{v}_1, \ldots, \mathbf{v}_n$ , and let

$$D = \operatorname{diag}(\lambda_1, \dots, \lambda_n) = \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{pmatrix}.$$

Then

$$X = PDP^{-1}$$

In this setting, we say X is **diagonalizable**.

One reason to care: Usually, matrix multiplication is computationally expensive, unless the matrices are very **sparse** (have lots of 0's). But diagonal matrices are *very* sparse! So if X is diagonalizable, then

$$X^{\ell} = (PDP^{-1})^{\ell} = (PDP^{-1})(PDP^{-1})\cdots(PDP^{-1}) = PD^{\ell}P^{-1};$$

and  $D^{\ell} = \operatorname{diag}(\lambda_1^{\ell}, \dots, \lambda_n^{\ell})$ . (By calculation!)

Important questions:

- When does an endomorphism even have such a nice basis?
- How do we find eigenvectors and eigenvalues?

### Finding eigenvalues and eigenvectors.

For a matrix  $X \in M_n(F)$  and a vector  $\mathbf{v} \in F^n$ , note that

$$X\mathbf{v} = \lambda \mathbf{v}$$
 if and only if  $\mathbf{0} = X\mathbf{v} - \lambda \mathbf{v} = (X - \lambda I_n)\mathbf{v}$ .

So

$$X\mathbf{v} = \lambda \mathbf{v}$$
 if and only if  $\mathbf{v} \in \mathcal{N}(X - \lambda I_n).$ 

Again,  $\mathbf{v} = \mathbf{0}$  is always a solution. But we're interested in *non-trivial* solutions! So  $\lambda \in F$  is an eigenvalue for X if and only if  $\mathcal{N}(X - \lambda I_n) \neq \{0\}$ .

### Determinant to the rescue!!!

 $\ker(X - \lambda I_n) \neq \{0\} \quad \Leftrightarrow \quad \operatorname{rank}(X - \lambda I_n) < n \quad \Leftrightarrow \quad \det(X - \lambda I_n) = 0.$ 

To find the eigenvalues of X, solve  $det(X - \lambda I_n) = 0$  for  $\lambda \in F$ .

Example. Back to 
$$X = \begin{pmatrix} -1 & 2 \\ -6 & 6 \end{pmatrix}$$
: We have  

$$X - \lambda I_2 = \begin{pmatrix} -1 & 2 \\ -6 & 6 \end{pmatrix} - \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix} = \begin{pmatrix} -1 - \lambda & 2 \\ -6 & 6 - \lambda \end{pmatrix}.$$

So

 $det(X - \lambda I_2) = (-1 - \lambda)(6 - \lambda) - 2(-6) = \lambda^2 - 5\lambda + 6 = (\lambda - 2)(\lambda - 3).$ Thus  $det(X - \lambda I_2) = 0$  when  $\lambda = 2$  or  $\lambda = 3$ ;

and hence these are exactly the two eigenvalues of X.

#### You try:

1. Find the eigenvalues of

$$X = \begin{pmatrix} 10 & -9 \\ 4 & -2 \end{pmatrix}, \quad Y = \begin{pmatrix} -2 & -1 \\ 5 & 2 \end{pmatrix}, \quad \text{and} \quad Z = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 0 & -2 \\ -1 & 2 & 3 \end{pmatrix}.$$

(See warmup.) Does it matter what F is?

2. If

$$X = \begin{pmatrix} 2 & -1 & -1 & 0\\ -1 & 3 & -1 & -1\\ -1 & -1 & 3 & -1\\ 0 & -1 & -1 & 2 \end{pmatrix}, \text{ then } \det(X - \lambda I_4) = \lambda(\lambda - 2)(\lambda - 4)^2.$$

This means that X has eigenvalues  $\lambda = 0$ ,  $\lambda = 2$ , and  $\lambda = 4$ .

Compute the nullspaces of  $X - 0I_4$  (this matrix is just X) and of  $X - 2I_4$ . (The computation of the nullspace of  $X - 4I_4$  is on the next page.)

First, we have

$$X - 4I_4 = \begin{pmatrix} 2-4 & -1 & -1 & 0\\ -1 & 3-4 & -1 & -1\\ -1 & -1 & 3-4 & -1\\ 0 & -1 & -1 & 2-4 \end{pmatrix} = \begin{pmatrix} -2 & -1 & -1 & 0\\ -1 & -1 & -1 & -1\\ -1 & -1 & -1 & -1\\ 0 & -1 & -1 & -2 \end{pmatrix}$$

Recall that to compute the nullspace of  $X - 4I_4$ , we should row reduce:

$$\begin{pmatrix} -2 & -1 & -1 & 0 & | & 0 \\ -1 & -1 & -1 & -1 & | & 0 \\ 0 & -1 & -1 & -1 & | & 0 \\ 0 & -1 & -1 & -2 & | & 0 \end{pmatrix} \xrightarrow{\operatorname{row}_1 \mapsto \operatorname{row}_1 - 2\operatorname{row}_2}_{\operatorname{row}_3 \mapsto \operatorname{row}_3 - \operatorname{row}_2} \begin{pmatrix} 0 & 1 & 1 & 2 & | & 0 \\ -1 & -1 & -1 & -1 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \\ 0 & -1 & -1 & -2 & | & 0 \end{pmatrix} \xrightarrow{\operatorname{row}_1 \mapsto \operatorname{row}_3 \mapsto \operatorname{row}_4 + \operatorname{row}_1} \begin{pmatrix} 0 & 1 & 1 & 2 & | & 0 \\ 1 & 1 & 1 & 1 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{pmatrix} \xrightarrow{\operatorname{row}_1 \leftrightarrow \operatorname{row}_2}_{\operatorname{row}_4 \mapsto \operatorname{row}_4 + \operatorname{row}_1} \begin{pmatrix} 1 & 1 & 1 & 2 & | & 0 \\ 1 & 1 & 1 & 1 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{pmatrix} \xrightarrow{\operatorname{row}_1 \leftrightarrow \operatorname{row}_2}_{\operatorname{row}_4 \mapsto \operatorname{row}_4 + \operatorname{row}_4 + \operatorname{row}_1} \begin{pmatrix} 1 & 0 & 0 & -1 & | & 0 \\ 0 & 1 & 1 & 2 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \\ \end{pmatrix} \cdot \operatorname{So} \begin{cases} x_1 - x_4 = 0, \\ x_2 + x_3 + 2x_4 = 0. \end{cases}$$

Thus, 
$$x_1 = x_4$$
 and  $x_2 = -x_3 - 2x_4$ , so that  

$$\mathcal{N}(X - 4I_2) = \left\{ \begin{pmatrix} x_4 \\ -x_3 - 2x_4 \\ x_3 \\ x_4 \end{pmatrix} \middle| x_3, x_4 \in F \right\} = F \left\{ \begin{pmatrix} 0 \\ -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ -2 \\ 0 \\ 1 \end{pmatrix} \right\}.$$

**Continuing with the example from Problem 2:** 

We just saw that matrix  $X = \begin{pmatrix} 2 & -1 & -1 & 0 \\ -1 & 3 & -1 & -1 \\ -1 & -1 & 3 & -1 \\ 0 & -1 & -1 & 2 \end{pmatrix}$  has eigenvalues  $\lambda = 0, 2,$ 

and 4; and that

$$\mathcal{N}(X - 0I_4) = F\{(1, 1, 1, 1)^t\},$$
  

$$\mathcal{N}(X - 2I_4) = F\{(-1, 0, 0, 1)^t\}, \text{ and }$$
  

$$\mathcal{N}(X - 4I_4) = F\{(0, -1, 1, 0)^t, (1, -2, 0, 1)\}.$$

One can check that

$$\mathcal{B} = \left\langle \begin{pmatrix} 1\\1\\1\\1 \end{pmatrix}, \begin{pmatrix} -1\\0\\0\\1 \end{pmatrix}, \begin{pmatrix} 0\\-1\\1\\0 \end{pmatrix}, \begin{pmatrix} 1\\-2\\0\\1 \end{pmatrix} \right\rangle$$

is a basis of  $F^4$  (so long as F isn't too small). So

$$X = PDP^{-1} \quad \text{where } P = \begin{pmatrix} 1 & -1 & 0 & 1 \\ 1 & 0 & -1 & -2 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{pmatrix} \text{ and } D = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 4 \end{pmatrix}$$

**General strategy:** 

- Find the eigenvalues of X by solving  $det(X \lambda I_n) = 0$  for  $\lambda$ .
- For each eigenvalue  $\lambda$ , compute a basis for  $\mathcal{N}(X \lambda I_n)$ .
- ▶ If this process results in finding n eigenvectors,  $\mathbf{v}_1, \ldots, \mathbf{v}_n$ , then A is diagonalizable. (This is a significant "if", but there's a reasonable backup plan.)

Let V be a finite-dimensional vector space over F, and let  $f: V \to V$  be an endomorphism. Back to the language of linear maps (instead of just matrices):

The eigenvalues of f are the roots of det(f – λ id). Note that the determinant det(f – λ id) will always be a polynomial in the variable λ. We call

$$p_f(x) = \det(f - x \text{ id})$$

the characteristic polynomial of f.

(The eigenvalues of f are exactly the roots of p<sub>f</sub>(x).)
 The eigenvectors of f associated to λ are those vectors in N(f - λ id). We call this space the eigenspace of f corresponding to λ, or just the λ-eigenspace of f, denoted

$$V_{\lambda} = V_{\lambda}(f) = \{ \mathbf{v} \in V \mid f(\mathbf{v}) = \lambda \mathbf{v} \}.$$

Note that because  $V_{\lambda}$  is a nullspace, it is a subspace of V.

For  $\lambda \in F$ , if  $(x - \lambda)^{\ell}$  is a factor of  $p_f(x)$ , but  $(x - \lambda)^{\ell+1}$  is not, we call  $\ell$  the (algebraic) multiplicity of  $\lambda$ , and denote it  $\ell = m_{\lambda}$ .

**Thm.** If  $\lambda$  is an eigenvalue of f, then  $1 \leq \dim(V_{\lambda}(f)) \leq m_{\lambda}$ .

If there is a basis of V consisting of eigenvectors of f, we call such a basis an eigenbasis, and say that f is diagonalizable (since there is a basis in which f is represented as a diagonal matrix).

Sufficient (but not necessary):  $\dim(V_{\lambda}(f)) = 1$  for all eigenvalues  $\lambda$ .

#### You try:

1. Above, you found the eigenvalues of

$$X = \begin{pmatrix} 10 & -9 \\ 4 & -2 \end{pmatrix} \quad \text{and} \quad Z = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 0 & -2 \\ -1 & 2 & 3 \end{pmatrix}.$$

Now compute the eigenspaces of each matrix.

[For X, the eigenspaces are subspaces of  $F^2$ ; the eigenspaces of Z are subspaces of  $F^3$ . You may assume that  $F = \mathbb{R}$  or  $\mathbb{C}$ .]

2. What are the eigenspaces of  $X = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$  if we're working over  $F = \mathbb{C}$ ? [Compute  $p_X(x)$  and find its roots; then compute  $V_\lambda(X) = \mathcal{N}(X - \lambda I_2)$  for each root  $\lambda$ .]

Does your answer change if we're working over  $F = \mathbb{R}$ ?

[Note: Geometrically, in  $\mathbb{R}^2$ , multiplication by X acts by rotating clockwise by  $\pi/2$ . Can you reconcile your answer with this geometric interpretation?]

3. Let  $\lambda \in F$ . Compute the eigenspaces of

$$X = \begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix} \quad \text{and of} \quad Y = \begin{pmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{pmatrix}$$