Lecture 4: Properties of vector spaces Subspaces Linear combinations Span

Unless otherwise stated: Assume F is a field with more than one element (so that $0 \neq 1$).

Last time: A field F, much like \mathbb{R} or \mathbb{C} , is a set with addition and multiplication, with lots of familiar properties (commutative, associative, and distributive properties, identity elements 0 and 1, inverses).

More examples: \mathbb{Q} , \mathbb{F}_2 .

A vector space V (over a field F), much like \mathbb{R}^n , is a set with addition and scaling from F, with properties like distributivity, associativity of scaling, and $1 \cdot \mathbf{v} = \mathbf{v}$ for all $\mathbf{v} \in V$. More examples: F^n , F[x], $\{f \in F[x] \mid \deg(f) \leq n\}$, $M_{m,n}(F)$. The trivial vector space (over any field F) is $0 = \{0\}$ (with 0 + 0 = 0 and $c \cdot 0 = 0$ for all $c \in F$).

We proved (in a specific case) that for all $\mathbf{v} \in V$, we have $V = \{(x, y, z) \in \mathbb{R}^3 \mid x + y + z = 0\}$

1. $0 \cdot v = 0$; and

Specific case: For any $(x, y, z) \in V$, we have

$$0 \cdot (x, y, z) = (0 \cdot x, 0 \cdot y, 0 \cdot z) = (0, 0, 0);$$

and (0,0,0) is the additive identity in \mathbb{R}^3 , and hence is the additive identity in $V \subseteq \mathbb{R}^3$.

2. $\mathbf{v} + (-1) \cdot \mathbf{v} = \mathbf{0}$.

Specific case: For any $(x, y, z) \in V$, we have

 $(-1)\cdot(x,y,z)=((-1)x,(-1)\cdot y,(-1)\cdot z)=(-x,-y,-z);$

and (-x, -y, -z) is the additive inverse of (x, y, z) in \mathbb{R}^3 , and hence is the additive inverse of (x, y, z) in $V \subseteq \mathbb{R}^3$.

More generally, let V be a vector space over a field F. Then for any $v \in V$, we have. . .

1. $0 \cdot v = 0$; and

General proof. Let $\mathbf{v} \in V$. Since 0 + 0 = 0 in F, we have

$$0 \cdot \mathbf{v} = (0+0) \cdot \mathbf{v} = 0 \cdot \mathbf{v} + 0 \cdot \mathbf{v} \tag{(*)}$$

by the distributive property. Whatever $0 \cdot \mathbf{v}$ is, it has an additive inverse $-(0 \cdot \mathbf{v})$; adding that to both sides gives

$$\begin{aligned} \mathbf{0} &= 0 \cdot \mathbf{v} + (-(0 \cdot \mathbf{v})) & \text{by the definition of } -(0 \cdot \mathbf{v}), \\ &= (0 \cdot \mathbf{v} + 0 \cdot \mathbf{v}) + (-(0 \cdot \mathbf{v})) & \text{by } (*), \\ &= 0 \cdot \mathbf{v} + (0 \cdot \mathbf{v} + (-(0 \cdot \mathbf{v}))) & \text{by associativity of } +, \\ &= 0 \cdot \mathbf{v}, & \text{by the definition of } -(0 \cdot \mathbf{v}). \end{aligned}$$

Hence, $\mathbf{0} = 0 \cdot \mathbf{v}$, as desired.

2. $\mathbf{v} + (-1) \cdot \mathbf{v} = \mathbf{0}$.

General proof. Let $\mathbf{v} \in V$. We have

$$\begin{split} \mathbf{v} + (-1) \cdot \mathbf{v} &= 1 \cdot \mathbf{v} + (-1) \cdot \mathbf{v}, & \text{since } 1 \cdot \mathbf{v} &= \mathbf{v}, \\ &= (1-1) \cdot \mathbf{v} & \text{by the distributive property, } = 0 \cdot \mathbf{v}. \end{split}$$

But $0 \cdot \mathbf{v} = \mathbf{0}$ by the previous part. And hence, $\mathbf{v} + (-1) \cdot \mathbf{v} = \mathbf{0}$, as desired. \Box

Lemma

Let F be a field, and let V be a vector space over F.

- 1. The additive identity is unique (i.e. if $\mathbf{a} + \mathbf{v} = \mathbf{v}$ and $\mathbf{b} + \mathbf{v} = \mathbf{v}$ for all $\mathbf{v} \in V$, then $\mathbf{a} = \mathbf{b}$).
- 2. For any $\mathbf{v} \in V$,
 - (a) the additive inverse of v is unique (i.e. if a + v = 0 and b + v = 0 then a = b);
 - (b) $0 \cdot \mathbf{v} = \mathbf{0}$; and \checkmark (c) $-\mathbf{v} = (-1) \cdot \mathbf{v}$
 - (c) $-\mathbf{v} = (-1) \cdot \mathbf{v}$.
- 3. For any $c \in F$, we have $c \cdot \mathbf{0} = \mathbf{0}$.

Subspaces

Let V be a vector space (over a field F), and let $W \subseteq V$ be a nonempty subset of V. We say W is a subspace of V if it is also a vector space under the same addition and scaling as V.

Necessary conditions:

- ▶ **0** ∈ W
- ▶ W is closed under addition and scaling: for all $\mathbf{u}, \mathbf{w} \in W$ and $c \in F$, we have

$$\mathbf{u} + \mathbf{w} \in W$$
 and $c \cdot \mathbf{u} \in W$.

For any $\mathbf{u}_1, \ldots, \mathbf{u}_n \in W$ and $a_1, \ldots, a_n \in F$, we call

$$a_1 \cdot \mathbf{u}_1 + \dots + a_n \cdot \mathbf{u}_n$$

a linear combination of $u_1, \ldots, u_n \in W$.

[Think: the sorts of expressions you'll get via iteratively applying scalars and sums.]

Prop. A subset $W \subseteq V$ is a subspace if and only if (1) it's non-empty, and (2) W is closed under linear combinations of any pair of elements (and hence under linear combinations in general).

Proof.

 (\Rightarrow) Assume W is a subspace...

(\Leftarrow) Assume $W \neq \emptyset$ and is closed under linear combinations...

Cor. (Subspace critreon) A subset $W \subseteq V$ is a subspace if and only if

(1) it's non-empty, and

(2) for all $\mathbf{u}, \mathbf{w} \in W$ and $c \in F$ we have $\mathbf{u} + c \cdot \mathbf{w} \in W$.

You try

Let $V = \mathbb{R}^2$, and let $a, b, c \in \mathbb{R}$. Consider $W = \{(x, y) \in \mathbb{R}^2 \mid ax + by = c\}$.

- (a) Under what circumstances could W be empty?
- (b) Under what circumstances could $\mathbf{0} \in W$?
- (c) Under what circumstances could W be closed under addition? [*Hint:* Assume $(x_1, y_1), (x_2, y_2) \in W$, so that $ax_1 + by_1 = c$ and $ax_2 + by_2 = c$. Now, take $(x, y) = (x_1, y_1) + (x_2, y_2) = (x_1 + x_2, y_1 + y_2)$ and plug it into ax + yb and compute.]
- (d) Under what circumstances would W be closed under scaling?

A linear equation

$$a_1x_1 + \dots + a_nx_n = b$$

is homogeneous if b = 0. (We say terms like $a_i x_i$ have degree 1 since $x_i = x_i^1$, and $b = b x_i^0$ has degree 0. So ever non-zero term in a linear equation has the same degree exactly when b = 0.)

Lemma. Consider a linear equation in n variables with coefficients in F. The solution set to that system is a subspace of F^n if and only if that equation is homogeneous. [Otherwise it's a "shift" of a v.s.]

Proof. Consider the equation $a_1x_1 + \cdots + a_nx_n = b$ (*). First, **0** is a solution exactly when b = 0. Next, if $\mathbf{y} = (y_1, \ldots, y_n)$ and $\mathbf{z} = (z_1, \ldots, z_n)$ are both solutions, that means

$$a_1y_1 + \dots + a_ny_n = b$$
 and $a_1z_1 + \dots + a_nz_n = b$.

So

$$a_1(y_1 + z_1) + \dots + a_n(y_n + z_n) = (a_1y_1 + a_1z_1) + \dots + (a_ny_n + a_nz_n)$$

= $(a_1y_1 + \dots + a_ny_n) + (a_1z_1 + \dots + a_nz_n)$
= $b + b = 2b.$

So y + z is a solution to (*) if and only if 2b = b, i.e. b = 0. Similarly, for $c \in F$,

$$a_1(cy_1) + \dots + a_n(cy_n) = c(a_1y_1 + \dots + a_ny_n) = cb.$$

So $c \cdot \mathbf{y}$ is a solution to (*) if and only if cb = b; so my solution set is closed under scaling by any $c \in F$ if and only if b = 0.

Lemma. Consider a linear equation in n variables with coefficients in F. The solution set to that system is a subspace of F^n if and only if that equation is homogeneous. [Otherwise it's a "shift" of a v.s.]

Lemma. Let U and W be subspaces of a vector space V (over a field F). Then $U \cap W$ is also a subspace of V. [See practice exercises.]

Proposition. Consider a system of linear equations with coefficients in *F*:

$$(*) \begin{cases} a_{1,1}x_1 + \dots + a_{1,n}x_n = b_1, \\ \vdots \\ a_{m,1}x_1 + \dots + a_{m,n}x_n = b_m. \end{cases}$$

Then the set of solutions W is a subspace of F^n if and only if $b_1 = \cdots = b_m = 0$ (all of the equations are homogeneous).

 $(\Rightarrow: \mathbf{0} \in W \text{ implies } b_i = 0 \text{ for all } i.)$

Note: From the reading, we saw that the solutions to (*) in general look like { (fixed particular solution) + (any solution to associated homogeneous) }

 $= \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} + \text{ (vector space of solutions to associated homogeneous)}$

Let V be a vector space (over F), and let $S \subseteq V$ be a subset of V. The closure of S (under linear combinations) is the set

 $[S] = \{a_1 s_1 + \dots + a_n s_n \mid n \in \mathbb{Z}_{\geq 0}, a_i \in F, s_i \in S\}.$

We also call [S] the span of S, which is also denoted FS or $\operatorname{span}_F(S)$.

Convention: If $S = \emptyset$, we set $[S] = \{0\}$, then empty linear combination. Example: Let $\mathbf{v} \in \mathbb{R}^3 - \mathbf{0}$ and let $S = \{\mathbf{v}\}$. Then

 $\mathbb{R}S = \mathbb{R}\mathbf{v} = \{t\mathbf{v} \mid t \in \mathbb{R}\}.$

Geometrically: [S] is a line through **0** in the direction of **v**. Example: Let $\mathbf{u}, \mathbf{v} \in \mathbb{R}^3 - \mathbf{0}$ (not parallel) and let $S = {\mathbf{u}, \mathbf{v}}$. Then $\mathbb{R}S = \mathbb{R}{\{\mathbf{u}, \mathbf{v}\}} = {s\mathbf{u} + t\mathbf{v} \mid s, t \in \mathbb{R}}.$

Geometrically: $\mathbb{R}S$ is a plane through **0** with direction vectors **u** and **v**.

Lemma. (Two.I.2.15)

Let V be a vector space over F, and let $S \subseteq V$.

Then FS is a subspace of V.

Proof. Use the subspace critereon.

Remark. The span FS is also the smallest vector space in V that contains S. (Uniqueness!)

Let V be a v.s. over F, and let $S \subseteq V$. Question: For a given $\mathbf{v} \in V$, how do we know if $\mathbf{v} \in FS$? Example: Let $V = \mathbb{R}[x]$, $F = \mathbb{R}$, and $S = \{p, q\}$, where $p = x^2 + 3x - 2$ and $q = 2x^2 + 5x - 3$.

Is $f = -x^2 - 4x + 1$ in $\mathbb{R}S$?

Namely, do there exist $a, b \in \mathbb{R}$ such that f = ap + bq? i.e.

$$-x^{2} - 4x + 1 = a(x^{2} + 3x - 2) + b(2x^{2} + 5x - 3)$$

= $(a + 2b)x^{2} + (3a + 5b)x + (-2a - 3b)?$

Two polynomials are equal exactly when the coefficients match; so comparing coefficients produces the three equations

$$\begin{cases} a+2b = -1 \\ 3a+5b = -4 \\ -2a-3b = 1 \end{cases} \text{ which encodes as } \begin{pmatrix} 1 & 2 & | & -1 \\ 3 & 5 & | & -4 \\ -2 & -3 & | & 1 \end{pmatrix}$$

To finish up: Put into reduced echelon form. If there are solutions, then yes, $f \in FS$. If not, then no, $f \notin FS$.