

ISOGENY FROM SU(2) TO SO(3)

This writeup constructs a 2-to-1 epimorphism $SU(2) \rightarrow SO(3)$, quickly demonstrating methods by example without full discussion. In general, a group that doubly covers an orthogonal group is called a *spin group*. See Paul Garrett's writeup

http://www-users.math.umn.edu/~garrett/m/v/sporadic_isogenies.pdf

for many more examples.

1. UNITARY GROUP AND ITS LIE ALGEBRA

For the unitary group $U(2) \subset GL_2(\mathbb{C})$, having Lie algebra $\mathfrak{u}(2) \subset M_2(\mathbb{C})$, the condition

$$1 = (\overline{e^{tx}})^\top e^{tx} = e^{t\bar{x}^\top} e^{tx} \quad \text{for } x \in \mathfrak{u}(2)$$

differentiates at 0 to $0 = \bar{x}^\top + x$; and conversely if $\bar{x}^\top = -x$ then

$$(\overline{e^{tx}})^\top e^{tx} = e^{t\bar{x}^\top} e^{tx} = e^{-tx} e^{tx} = 1.$$

Thus the Lie algebra consists of the skew hermitian matrices. Here $U(2)$ and $\mathfrak{u}(2)$ are a real Lie group and Lie algebra notwithstanding their complex entries. Their shared real dimension is 4. The Lie algebra $\mathfrak{su}(2)$ of the special unitary group $SU(2)$ carries the additional condition that the trace vanishes,

$$\mathfrak{su}(2) = \{ x \in M_2(\mathbb{C}) : \bar{x}^\top = -x, \operatorname{tr} x = 0 \}.$$

This reduces its dimension to 3, also the manifold dimension of $SU(2)$. Here the argument is that the condition $\det e^{tx} = 1$ is $e^{t \operatorname{tr} x} = 1$, which differentiates at $t = 0$ to $\operatorname{tr} x = 0$; and conversely if $\operatorname{tr} x = 0$ then $\det e^{tx} = e^{t \operatorname{tr} x} = e^0 = 1$.

The $\mathfrak{su}(2)$ conditions $\bar{x}^\top = -x$ and $\operatorname{tr} x = 0$ are preserved under addition, real scaling, and the Lie bracket. For example,

$$(\overline{rx})^\top = \bar{r} \bar{x}^\top = -r x \quad \text{for real } r,$$

and

$$(\overline{xy - yx})^\top = \bar{y}^\top \bar{x}^\top - \bar{x}^\top \bar{y}^\top = (-y)(-x) - (-x)(-y) = yx - xy = -(xy - yx).$$

2. INNER PRODUCT, INVARIANCE

A real symmetric bilinear inner product on $\mathfrak{su}(2)$ is

$$\langle \cdot, \cdot \rangle : \mathfrak{su}(2) \times \mathfrak{su}(2) \rightarrow \mathbb{R}, \quad \langle x, y \rangle = \operatorname{Re}(\operatorname{tr}(xy)).$$

The group $SU(2)$ acts on the algebra $\mathfrak{su}(2)$ by conjugation,

$$g \cdot x = gxg^{-1},$$

and this action preserves the inner product,

$$\langle g \cdot x, g \cdot y \rangle = \langle x, y \rangle.$$

Indeed, to see that $g \cdot x$ again lies in $\mathfrak{su}(2)$ for all $g \in SU(2)$ and $x \in \mathfrak{su}(2)$, note that because g and $e^{\mathbb{R}x}$ and g^{-1} lie in $SU(2)$, also

$$e^{\mathbb{R}gxg^{-1}} = ge^{\mathbb{R}x}g^{-1} \quad \text{lies in } SU(2),$$

and to see that the action preserves the inner product, compute that

$$\langle g \cdot x, g \cdot y \rangle = \operatorname{Re}(\operatorname{tr}(g x g^{-1} g y g^{-1})) = \operatorname{Re}(\operatorname{tr}(x y)) = \langle x, y \rangle.$$

Note that the results in this section rely only on general Lie group and Lie algebra properties, not on any particulars of the specific Lie group $\mathbf{SU}(2)$ and its Lie algebra $\mathfrak{su}(2)$.

3. ORTHOGONAL BASIS, GROUP ACTION, ISOGENY

The $\mathfrak{su}(2)$ -basis

$$x_1 = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix}, \quad x_2 = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \quad x_3 = \begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix}$$

is orthogonal under the inner product, with $\langle x_i, x_i \rangle = -2$ for $i = 1, 2, 3$. For example,

$$\langle x_1, x_1 \rangle = \operatorname{Re}(\operatorname{tr} \left(\begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \right)) = -2, \quad \langle x_2, x_3 \rangle = \operatorname{Re}(\operatorname{tr} \left(\begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} \right)) = 0.$$

Thus we have the 3×3 matrix

$$[\langle x_i, x_j \rangle] = -2I_3.$$

The action of any group element

$$g = \begin{bmatrix} a & b \\ -\bar{b} & \bar{a} \end{bmatrix} = \begin{bmatrix} \alpha_1 + i\alpha_2 & \beta_1 + i\beta_2 \\ -\beta_1 + i\beta_2 & \alpha_1 - i\alpha_2 \end{bmatrix} \in \mathbf{SU}(2)$$

on the basis elements is a matter of direct computation, albeit a bit tedious,

$$\begin{aligned} g \cdot x_1 &= (\alpha_1^2 + \alpha_2^2 - \beta_1^2 - \beta_2^2)x_1 + 2(\alpha_2\beta_1 + \alpha_1\beta_2)x_2 + 2(\alpha_2\beta_2 - \alpha_1\beta_1)x_3 \\ g \cdot x_2 &= 2(\alpha_2\beta_1 - \alpha_1\beta_2)x_1 + (\alpha_1^2 - \alpha_2^2 + \beta_1^2 - \beta_2^2)x_2 + 2(\alpha_1\alpha_2 + \beta_1\beta_2)x_3 \\ g \cdot x_3 &= 2(\alpha_1\beta_1 + \alpha_2\beta_2)x_1 + 2(-\alpha_1\alpha_2 + \beta_1\beta_2)x_2 + (\alpha_1^2 - \alpha_2^2 - \beta_1^2 + \beta_2^2)x_3. \end{aligned}$$

This shows that the map from $\mathbf{SU}(2)$ to the special orthogonal group $\mathbf{SO}(3)$ is the quadratic map

$$\varphi : g \mapsto \begin{bmatrix} \alpha_1^2 + \alpha_2^2 - \beta_1^2 - \beta_2^2 & 2(\alpha_2\beta_1 - \alpha_1\beta_2) & 2(\alpha_1\beta_1 + \alpha_2\beta_2) \\ 2(\alpha_2\beta_1 + \alpha_1\beta_2) & \alpha_1^2 - \alpha_2^2 + \beta_1^2 - \beta_2^2 & 2(-\alpha_1\alpha_2 + \beta_1\beta_2) \\ 2(-\alpha_1\beta_1 + \alpha_2\beta_2) & 2(\alpha_1\alpha_2 + \beta_1\beta_2) & \alpha_1^2 - \alpha_2^2 - \beta_1^2 + \beta_2^2 \end{bmatrix}.$$

Let the matrix in the previous display be denoted A_g . To argue that A_g is orthogonal, introduce the map that converts elements of $\mathfrak{su}(2)$ into \mathbb{R}^3 -vectors,

$$v : \mathfrak{su}(2) \xrightarrow{\sim} \mathbb{R}^3, \quad v\left(\sum_{i=1}^3 c_i x_i\right) = \sum_{i=1}^3 c_i e_i, \quad (e_i \text{ the standard basis vectors}).$$

Because A_g is the matrix of the g -action, we have a commutative diagram

$$\begin{array}{ccc} \mathfrak{su}(2) & \xrightarrow{g} & \mathfrak{su}(2) \\ v \downarrow & & \downarrow v \\ \mathbb{R}^3 & \xrightarrow{A_g} & \mathbb{R}^3 \end{array}$$

which is to say,

$$(1) \quad A_g v(x) = v(g \cdot x), \quad g \in \mathbf{SU}(2), \quad x \in \mathfrak{su}(2).$$

And note that by our inner product calculations on the $\mathfrak{su}(2)$ basis elements,

$$(2) \quad \langle x, x' \rangle_{\mathfrak{su}(2)} = -2\langle v(x), v(x') \rangle_{\mathbb{R}^3}, \quad x, x' \in \mathfrak{su}(2).$$

Now compute for any $g \in \mathbf{SU}(2)$ and any $x, x' \in \mathfrak{su}(2)$, recalling for the third equality that the $\mathbf{SU}(2)$ action preserves the $\mathfrak{su}(2)$ inner product,

$$\begin{aligned} \langle A_g v(x), A_g v(x') \rangle_{\mathbb{R}^3} &= \langle v(g \cdot x), v(g \cdot x') \rangle_{\mathbb{R}^3} && \text{by (1)} \\ &= (-1/2)\langle g \cdot x, g \cdot x' \rangle_{\mathfrak{su}(2)} && \text{by (2)} \\ &= (-1/2)\langle x, x' \rangle_{\mathfrak{su}(2)} && \text{as just recalled} \\ &= \langle v(x), v(x') \rangle_{\mathbb{R}^3} && \text{by (1) again.} \end{aligned}$$

This shows that A_g is orthogonal.

The map $g \mapsto A_g$ is innately a homomorphism, because the action property $(gg') \cdot x = g \cdot (g' \cdot x)$ for $g, g' \in \mathbf{SU}(2)$ and $x \in \mathfrak{su}(2)$ combines with the fact that matrix multiplication is compatible with linear map composition to give $A_{gg'} = A_g A_{g'}$.

To determine the kernel of the map $g \mapsto A_g$, note that the diagonal conditions

$$\alpha_1^2 + \alpha_2^2 - \beta_1^2 - \beta_2^2 = \alpha_1^2 - \alpha_2^2 + \beta_1^2 - \beta_2^2 = \alpha_1^2 - \alpha_2^2 - \beta_1^2 + \beta_2^2 = 1$$

are $\alpha_1^2 - 1 = \alpha_2^2 = \beta_1^2 = \beta_2^2$. Now the $(1, 2)$ -entry condition $\alpha_2 \beta_1 - \alpha_1 \beta_2 = 0$ is $\pm \beta_2^2 = \pm \sqrt{\beta_2^2 + 1} \beta_2$; if $\beta_2 \neq 0$ then canceling β_2 and then squaring both sides gives the impossible condition $\beta_2^2 = \beta_2^2 + 1$, so $\beta_2 = 0$. This forces $g = \pm 1_2$. Conversely, if $g = \pm 1$ then $A_g = 1$. In sum, the map has kernel is $\pm 1_2$.

Because the manifold dimension 3 of $\mathbf{O}(3)$ matches that of the connected group $\mathbf{SU}(2)$, the map $g \mapsto A_g$ surjects to the connected component $\mathbf{SO}(3)$ of its codomain.