



Homotopy invariance of de Rham cohomology

Wednesday quiz

Don't forget the Wednesday quiz.

k -th de Rham cohomology group

$$\dots \rightarrow \Omega^{k-1}M \xrightarrow{d_{k-1}} \Omega^k M \xrightarrow{d_k} \Omega^{k+1}M \rightarrow \dots$$

$$H^k M := \ker d_k / \operatorname{im} d_{k-1}$$

We've seen that

$$H^k \mathbb{R} = \begin{cases} \mathbb{R} & \text{if } k = 0 \\ 0 & \text{if } k > 0, \end{cases}$$

and $H^n M \neq 0$ if M is a closed n -manifold.

Homotopy

Let $f, g: M \rightarrow N$. Then f is *homotopic* to g , denoted $f \sim g$ if there exists $h: [0, 1] \times M \rightarrow N$ such that

$$h(0, x) = f(x)$$

$$h(1, x) = g(x).$$

Example. $M = \mathbb{R}^2 \setminus \{(0, 0)\}$, and

$$h: [0, 1] \times M \rightarrow M$$

$$p \mapsto (1 - t)p + t \frac{p}{|p|}.$$

We have $h(0, x) = \text{id}_M(x)$.

Let $r(x) = h(1, x)$. Then (i) $r: M \rightarrow S^1 \subset \mathbb{R}^2$, (ii) if $x \in S^1$, then $r(x) = x$, and (iii) $r \sim \text{id}_M$.

The mapping r is an example of a *deformation retraction*. We will see that this means $H^k M = H^k S^1$ for all k .

Homotopy invariance theorem

If $f, g: M \rightarrow N$, and $f \sim g$, then

$$f^* = g^*: H^k N \rightarrow H^k M$$

for all k .

Homotopy equivalence

Let $f: M \rightarrow N$ and $g: N \rightarrow M$. Suppose that

$$g \circ f \sim \text{id}_M \quad \text{and} \quad f \circ g \sim \text{id}_N.$$

Then, by the homotopy invariance theorem,

$$(g \circ f)^* = \text{id}_M^* = \text{id}_{H^k M}: H^k M \rightarrow H^k M$$

$$(f \circ g)^* = \text{id}_N^* = \text{id}_{H^k N}: H^k N \rightarrow H^k N.$$

Thus,

$$(g \circ f)^* = f^* \circ g^* = \text{id}_{H^k M}$$

$$(f \circ g)^* = g^* \circ f^* = \text{id}_{H^k N}$$

So f^* and g^* are inverse isomorphisms. Therefore, ...

Homotopy equivalence

Let $f: M \rightarrow N$ and $g: N \rightarrow M$. Suppose that

$$g \circ f \sim \text{id}_M \quad \text{and} \quad f \circ g \sim \text{id}_N.$$

Then

$$H^k M \approx H^k N$$

for all k .

Example

Let $M = \mathbb{R}^2 \setminus \{(0,0)\}$, and define

$$\begin{array}{ll} \iota: S^1 \rightarrow M & r: M \rightarrow S^1 \\ (x,y) \mapsto (x,y) & p \mapsto \frac{p}{|p|}. \end{array}$$

Then, $r \circ \iota = \text{id}_{S^1}$, and $\iota \circ r \stackrel{h}{\sim} \text{id}_M$ by the h in our first example.

By homotopy equivalence, it follows that

$$H^k M \approx H^k S^1.$$

We will soon see (\star Mayer-Vietoris \star) that

$$H^k S^1 = \begin{cases} \mathbb{R} & \text{if } k = 0, 1 \\ 0 & \text{otherwise.} \end{cases}$$

Proof of homotopy invariance theorem

Idea: Find collection of mappings $s: \Omega^k N \rightarrow \Omega^{k-1} M$

$$\begin{array}{ccccccc} \dots & \xrightarrow{d} & \Omega^{k-1} N & \xrightarrow{d} & \Omega^k N & \xrightarrow{d} & \Omega^{k+1} N & \xrightarrow{d} & \dots \\ & \searrow s & & \searrow s & & \searrow s & & \searrow s & \\ \dots & \xrightarrow{d} & \Omega^{k-1} M & \xrightarrow{d} & \Omega^k M & \xrightarrow{d} & \Omega^{k+1} M & \xrightarrow{d} & \dots \end{array}$$

such that for all $\omega \in \Omega^k N$,

$$g^* \omega - f^* \omega = (sd + ds)\omega.$$

If ω is closed, i.e., $d\omega = 0$, then

$g^* \omega - f^* \omega = (sd + ds)\omega = d(s\omega)$. Therefore, $f^* \omega$ and $g^* \omega$ differ by an element in the image of d_{k-1} . So $[f^* \omega] = [g^* \omega]$ for all ω .

Hence, $f^* = g^*$.



Prism operator

The key ingredient for constructing s is the *prism operator*.

$$P: \Omega^k([0, 1] \times M) \rightarrow \Omega^{k-1}M$$
$$\omega \mapsto \int_{t=0}^1 \omega \left(\frac{\partial}{\partial t}, - \right).$$

Example. $\omega = (x + 3t^2) dt \wedge dx \in \Omega^2([0, 1] \times \mathbb{R})$.

$$P\omega = \left(\int_{t=0}^1 (x + 3t^2) dt \right) \wedge dx = (x + 1) dx.$$

(In general, integrate with respect to t and then drop the dt .)

If ω does not involve dt , then $P\omega = 0$, e.g. if

$w = (x + y) dx \wedge dy \in \Omega^2([0, 1] \times \mathbb{R}^2)$, then $Pw = 0$.

Proof of homotopy invariance theorem

For each $t \in [0, 1]$, define

$$\begin{aligned} i_t: M &\rightarrow [0, 1] \times M \\ x &\mapsto (t, x). \end{aligned}$$

We have that $(h \circ i_0) = f$ and $(h \circ i_1) = g$.

A straightforward calculation in coordinates (see our text) gives

$$\iota_1^* - \iota_0^* = dP - Pd.$$

Define $s = P \circ h^*$:

$$\Omega^k N \xrightarrow{h^*} \Omega^k([0, 1] \times M) \xrightarrow{P} \Omega^{k-1} M,$$

Then $g^* - f^* = i_1^* h^* - i_0^* h^* = (i_1^* - i_0^*) h^* = (dP + Pd) h^* = d(Ph^*) + (Ph^*)d = ds + sd$. (Note: d commutes with pullbacks.) □