Definition of a manifold

Definition

An *n*-dimensional differentiable manifold is a pair (M, D) consisting of a second countable Hausdorff topological space M with an *n*-dimensional differentiable structure D.

Essential vocabulary:

- charts (U, h), locally Euclidean, choosing coordinates
- transition function, change of coordinates
- differentiably related charts (U, h) and (V, k)
- differentiable atlas, equivalent atlases
- differentiable structure

Projective plane

 $\mathbb{P}^2=~\mbox{one-dimensional subspaces of }\mathbb{R}^3$

=~ lines through the origin in \mathbb{R}^3

$$= \mathbb{R}^3 \setminus \{(0,0,0)\} \bigg/ [(x,y,z) \sim \lambda(x,y,z) \text{ for } \lambda \neq 0].$$

quotient topology

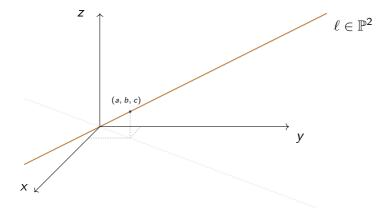
We say (x, y, z) are the *homogeneous coordinates* for a point in \mathbb{P}^2 .

Which of the following represent the point $(2, 4, 5) \in \mathbb{P}^2$?

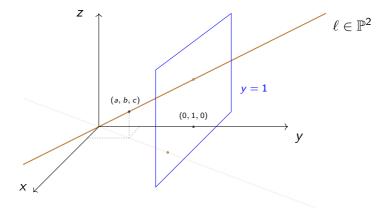
(a) (4,8,10)
(b) (1,2,2)
(c) (1/2,1,5/4).

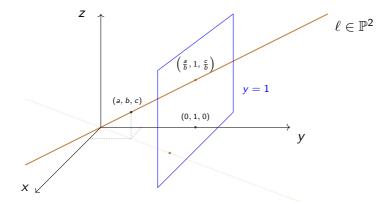
Solution: (a) and (c).

$$\mathbb{P}^2 = \mathbb{R}^3 \setminus \{(0,0,0)\} \Big/ [(x,y,z) \sim \lambda(x,y,z) ext{ for } \lambda
eq 0]$$



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eq 0]$$





 $(a, b, c) = \left(\frac{a}{b}, 1, \frac{c}{b}\right) \mapsto \left(\frac{a}{b}, \frac{c}{b}\right)$

$$\mathbb{P}^2 = \mathbb{R}^3 \setminus \{(0,0,0)\} \ \Big/ \ [(x,y,z) \sim \lambda(x,y,z) ext{ for } \lambda
eq 0] \ U_y := ig\{(x,y,z) \in \mathbb{P}^2 : y
eq 0ig\}$$

$$\phi_y \colon U_y \to \mathbb{R}^2$$

 $(a, b, c) \mapsto \left(\frac{a}{b}, \frac{c}{b}\right)$

$$\phi_y^{-1}(u,v)=(u,1,v)$$

$$\mathbb{P}^2 = \mathbb{R}^3 \setminus \{(0,0,0)\} / [(x,y,z) \sim \lambda(x,y,z) ext{ for } \lambda
eq 0]$$
 $U_x, \quad U_y, \quad U_z$

$$\begin{split} \phi_{x} \colon U_{x} \to \mathbb{R}^{2} & \phi_{y} \colon U_{y} \to \mathbb{R}^{2} & \phi_{z} \colon U_{z} \to \mathbb{R}^{2} \\ (a, b, c) \mapsto \left(\frac{b}{a}, \frac{c}{a}\right) & (a, b, c) \mapsto \left(\frac{a}{b}, \frac{c}{b}\right) & (a, b, c) \mapsto \left(\frac{a}{c}, \frac{b}{c}\right) \\ \phi_{x}^{-1}(u, v) &= (1, u, v) & \phi_{y}^{-1}(u, v) = (u, 1, v) & \phi_{z}^{-1}(u, v) = (u, v, 1) \end{split}$$

standard atlas: $\mathcal{U} = \{(U_x, \phi_x), (U_y, \phi_y), (U_z, \phi_z)\}$

What are the coordinates of $(4, 2, 16) \in \mathbb{P}^2$ with respect to the chart (U_y, ϕ_y) :

(a) (2,8)
(b) (2,1)
(c) (1/2,4).
Solution: (a).

Other models for \mathbb{P}^2

- ▶ 2-sphere w/ antipodal points identified: $\mathbb{P}^2 = S^2/[p \sim -p]$
- upper hemisphere w/antipodal points on equator identified
- closed square with "antipodal" boundary points identified



Projective *n*-space

$$\mathbb{P}^n$$
 = one-dimensional subspaces of \mathbb{R}^{n+1}

= lines through the origin in \mathbb{R}^{n+1}

$$= \mathbb{R}^{n+1} \setminus \{0\} / [p \sim \lambda p \text{ for } \lambda \neq 0]$$
$$= S^n / [p \sim -p]$$

Projective *n*-space

Charts

$$U_i = \{(x_1, \dots, x_{n+1}) : x_i \neq 0\}$$
 for $i = 1, \dots, n+1$

$$\phi_i \colon U_i \to \mathbb{R}^n$$

$$(x_1, \dots, x_{n+1}) \mapsto \left(\frac{x_1}{x_i}, \dots, \frac{\widehat{x_i}}{x_i}, \dots, \frac{x_{n+1}}{x_i}\right)$$

Thanks!