

# Math 322

March 11, 2022

## Dependence on parameters

**Theorem.** Let  $E$  be an open subset of  $\mathbb{R}^{n+m}$  containing the point  $(x_0, \mu_0)$  where  $x_0 \in \mathbb{R}^n$  and  $\mu_0 \in \mathbb{R}^m$ , and assume  $f \in C^1(E)$ .

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$$\begin{aligned}x' &= f(x, \mu) \\ x(0) &= y\end{aligned}$$

has a unique solution  $x = x(t, y, \mu)$  with  $x \in C^1(R)$  where  $R := [-a, a] \times N(x_0) \times N(\mu_0)$ .

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## Stable manifold theorem

**Theorem.** (Stable manifold theorem.) Let  $E \subseteq \mathbb{R}^n$  and let  $f \in C^1(E)$ . Suppose that  $f(0) = 0$  and that  $Df_0$  has  $k$  eigenvalues with negative real part and  $n - k$  eigenvalues with positive real part.

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Then there exists a  $k$ -dimensional differentiable manifold  $S$  tangent to the stable subspace  $E^s$  of the linearized system  $x' = Df_0(x)$  at 0, and there exists an  $(n - k)$ -dimensional differentiable manifold  $U$  tangent to the unstable space  $E^u$  of the linearized system

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$$\lim_{t \rightarrow \infty} \phi_t(x_0) = 0$$

for any  $x_0 \in S$  and

$$\lim_{t \rightarrow -\infty} \phi_t(x_0) = 0$$

for any  $x_0 \in U$ .

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$$(i) \phi_0(x_0) = x_0 \quad (ii) \phi_s(\phi_t(x_0)) = \phi_{s+t}(x_0) \quad (iii) \phi_{-t}(\phi_t(x_0)) = x_0$$

## Metric space

**Definition.** A *metric space* is a set  $X$  with a *distance function* or *metric*,

$$d: X \times X \rightarrow \mathbb{R}$$

that is positive definite, symmetric, and obeys the triangle inequality:

1.  $d(x, y) \geq 0$  with  $d(x, y) = 0$  if and only if  $x = y$
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3.  $d(x, y) \leq d(x, z) + d(z, y)$ .

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Every metric space  $(X, d)$  is a topological space where a subset  $U \subseteq X$  is *open* if for each  $u \in U$ , there exists  $r > 0$  such that the open ball of radius  $r$  centered at  $u$  is contained in  $U$ :

$$B(u, r) := \{x \in X : d(u, x) < r\} \subseteq U.$$

# Manifold

**Definition.** An  $n$ -dimensional differentiable manifold is a connected metric space<sup>2</sup>  $M$  and an open covering  $\{U_\alpha\}$  (so for each  $\alpha$  in some index set,  $U_\alpha$  is an open subset of  $M$  and  $M = \cup_\alpha U_\alpha$ ) such that:

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<sup>2</sup>More generally,  $M$  could be a second-countable Hausdorff topological space.



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2. if  $U_\alpha \cap U_\beta \neq \emptyset$ , the mapping

$$h_\beta \circ h_\alpha^{-1}: h_\alpha(U_\alpha \cap U_\beta) \rightarrow h_\beta(U_\alpha \cap U_\beta)$$

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Each pair  $(h_\alpha, U_\alpha)$  is called a *chart*, and the collection of charts is called an *atlas*. The mapping  $h_\beta \circ h_\alpha^{-1}$  are *transition functions*.

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