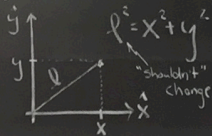


physics: identify a target invariant, build transformations that support it.

example:



define simple (but general) linear transformation:

$$\bar{x} = Ax + By, \quad \bar{y} = Fx + Gy$$

for const.s $\{A, B, F, G\}$, w/ shared origin. Demand:

$$\bar{r}^2 \equiv \bar{x}^2 + \bar{y}^2 = x^2 + y^2 = r^2$$

so that lens are unchanged.

$$\bar{x}^2 + \bar{y}^2 = (A^2 + F^2)\bar{x}^2 + 2xy(AB + FG) + (B^2 + G^2)\bar{y}^2$$

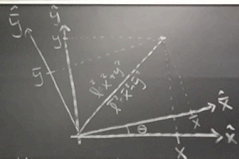
$$= x^2 + y^2 \text{ gives 3 eqns.}$$

$$A^2 + F^2 = 1, AB + FG = 0, B^2 + G^2 = 1$$

we are left w/ 1 free parameter, " θ "

$$A = \cos\theta, F = -\sin\theta, B = \sin\theta, G = \cos\theta$$

$$\begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} = \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \text{ rotation of axes} \\ \text{through an angle } \theta$$

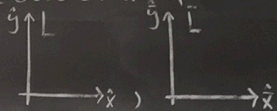


the relation can be inverted: $\theta \rightarrow -\theta$.

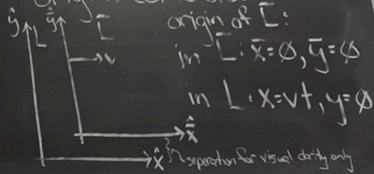
$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix}$$

are there other "invariants" of interest? "Special relativity" provides one. We need some setup to see it

2 sets of axes, L & L' :



L' travels to the right, through L , w/ constant speed v . At $t=0$, the origins coincide.



origin of L' :

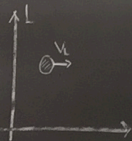
in L' : $\bar{x}=0, \bar{y}=0$

in L : $x=vt, y=0$

\bar{x} separator for visual clarity only

Experiment 1

at $t=0$, as origins coincide,
throw a ball w/ speed v_L
relative to L:



? at time t - where
is the ball in L?

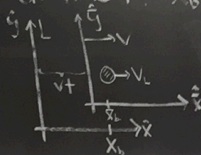
$$x_b = v_L t$$

speed of ball relative to E:

$$v_E = v_L - v \quad \left(\begin{array}{l} \text{check: if } v_L = v, \\ v_E = 0 \end{array} \right)$$

? where is the ball in E

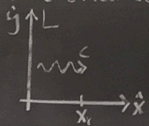
at time t ? $\bar{x}_b = v_E t = (v_L - v) t$



(as drawn here,
 $v_L > v$.)

Experiment 2

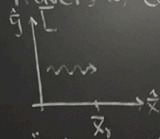
at $t=0$, as origins coincide, throw a "photon" (turn on a flashlight pointing along the shared \hat{x}, \hat{x} axis) at speed c .



At time t , photon is at

$x_1 = ct$, travels at constant speed c relative to L

the observation, in \bar{L} , is that the photon also travels w/ constant speed c ...



$$\bar{x}_1 = c \bar{t}$$

time, as measured in \bar{L}

1. "velocity addition" must change
2. L & \bar{L} measure time differently.

comparing the "photons"
location in L, \bar{L} :

$$x_s = ct \Rightarrow x_s^2 - (ct)^2 = 0$$

$$\bar{x}_s = c\bar{t} \Rightarrow \bar{x}_s^2 - (c\bar{t})^2 = 0$$

$$\bar{x}_s^2 - (c\bar{t})^2 = x_s^2 - (ct)^2$$

idea - this holds $\forall (x_s, ct)$ & $(\bar{x}_s, c\bar{t})$

(clearly true for c , but why at
other speeds?)

$$\boxed{\bar{x}^2 - (c\bar{t})^2 = x^2 - (ct)^2}$$

a quadratic, similar in form
to $\bar{x}^2 + \bar{y}^2 = x^2 + y^2$
except for that sign ...

Transformation

What relation between $\bar{x}, c\bar{t}$ & x, ct preserves this quantity?

$$\bar{x} = Ax + B(ct)$$

$$c\bar{t} = Fx + G(ct)$$

again start w/ a linear relation, leaving the $x-ct$ origin fixed.

demand: $\bar{x}^2 - (c\bar{t})^2 = x^2 - (ct)^2$:

$$\begin{aligned} \bar{x}^2 - (c\bar{t})^2 &= (A^2 - F^2)x^2 + 2xct(AB - FG) + (B^2 - G^2)(ct)^2 \\ &= x^2 - (ct)^2 \end{aligned}$$

gives, again, 3 eqns in 4 "unknowns"

$$A^2 - F^2 = 1, \quad AB - FG = 0, \quad G^2 - B^2 = 1$$

$$A = \cosh \eta, \quad F = \sinh \eta, \quad G = \cosh \eta, \quad B = \sinh \eta$$

$$\begin{pmatrix} ct \\ \bar{x} \end{pmatrix} = \begin{pmatrix} \cosh \eta & \sinh \eta \\ \sinh \eta & \cosh \eta \end{pmatrix} \begin{pmatrix} ct \\ x \end{pmatrix}$$

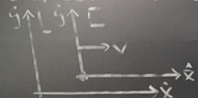
w/ inverse given by $\eta \rightarrow -\eta$

$$\begin{pmatrix} ct \\ x \end{pmatrix} = \begin{pmatrix} \cosh \eta & -\sinh \eta \\ -\sinh \eta & \cosh \eta \end{pmatrix} \begin{pmatrix} ct \\ \bar{x} \end{pmatrix}$$

the "Lorentz" transformation

how is η related to this picture?

pick a point, any point



origin of \bar{L} : $\bar{x} = 0$ ($\bar{y} = 0$) in \bar{L}

$x = vt$ ($y = 0$) in L

$$\bar{x} = x \cosh \eta + ct \sinh \eta$$

$$0 = vt \cosh \eta + ct \sinh \eta$$

$$\Rightarrow \boxed{\tanh \eta = -\frac{v}{c}}$$

from $\tanh \eta = \frac{v}{c}$, and $\cosh^2 \eta - \sinh^2 \eta = 1$, we learn that:

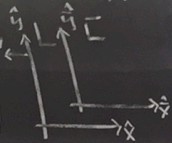
$$\cosh \eta = \frac{1}{\sqrt{1 - v^2/c^2}} \equiv \gamma$$

$$\sinh \eta = \frac{-v/c}{\sqrt{1 - v^2/c^2}} = -\frac{v}{c} \gamma$$

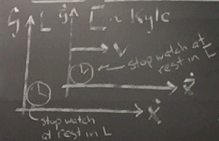
η is the "rapidity"
the Lorentz transformation is:

$$\begin{pmatrix} ct \\ \bar{x} \end{pmatrix} = \begin{pmatrix} \gamma & -\frac{v}{c}\gamma \\ -\frac{v}{c}\gamma & \gamma \end{pmatrix} \begin{pmatrix} ct \\ x \end{pmatrix} \quad \begin{array}{l} \text{w/ inverse} \\ \text{obtained via} \\ v \rightarrow -v: \end{array}$$

$$\begin{pmatrix} ct \\ x \end{pmatrix} = \begin{pmatrix} \gamma & \frac{v}{c}\gamma \\ \frac{v}{c}\gamma & \gamma \end{pmatrix} \begin{pmatrix} ct \\ \bar{x} \end{pmatrix}$$



Time Dilation



origins coincide,
synch:
 $t = 0, \bar{t} = 0$

time \bar{t} elapses on Kyle's stopwatch-how much

time has passed on the clock at rest in L?

$$\text{Lorentz: } ct = \gamma c\bar{t} + v\gamma\bar{x}$$

$$\bar{t} = \frac{1}{\sqrt{1-v^2/c^2}} \bar{t} > \bar{t}$$

$\bar{x} = 0$: the location of the clock in L

At Kyle's normal pace: $v = \frac{4}{5}c$

$\bar{t} = \frac{5}{3}\bar{t} \leftarrow$ for 1 year in L, } Suster is younger
 $\frac{5}{3} = 1.7$ years in L

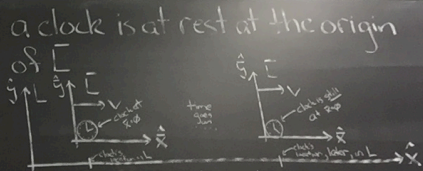
Proper Time

the invariant:

$$\bar{x}^2 - (c\bar{t})^2 = x^2 - (ct)^2$$

holds for infinitesimal intervals.

$$d\bar{x}^2 - c^2 d\bar{t}^2 = dx^2 - c^2 dt^2$$



in \bar{L} , the clock is at rest, $d\bar{x}=0$ and ticks off time $d\bar{t}$

in L , the clock is moving, $dx \neq 0$, and ticks off time dt .

the intervals are related:

$$d\bar{x}^2 - c^2 d\bar{t}^2 = dx^2 - c^2 dt^2$$

$$\text{or } c^2 d\bar{t}^2 = c^2 dt^2 - dx^2$$

the clock in \bar{L} records the "proper" (own) time. It is at rest in \bar{L} , at least instantaneously. Proper time typically denoted τ .

Parametrizing Motion.

common, in physics, to use time as a parameter to describe motion, $x(t)$. Could we instead use τ ? From

$$c^2 d\tau^2 = c^2 dt^2 - dx^2$$

if we use r to param., $x(r)$,
then: $dx = \frac{dx}{dr} dr$, and we must
also parametrize the "movement"
in time, $t(r)$, w/ $dt = \frac{dt}{dr} dr$, and

$$c^2 dr^2 = \left[c^2 \left(\frac{dt}{dr} \right)^2 - \left(\frac{dx}{dr} \right)^2 \right] dt^2 \quad \text{or}$$

an affine parametrization
for $v_r = \left(\frac{dx}{dt} \right)$

We can still use t , $x(t)$ has.

$$dx = \frac{dx}{dt} dt \quad \text{smaller time-param'd velocity component}$$

then

$$c^2 dt^2 = c^2 dt^2 - \left(\frac{dx}{dt} \right)^2 dt^2$$

or

$$dt^2 = \frac{dr^2}{\left(1 - \frac{(dx/dr)^2}{c^2} \right)^2} \quad \text{our time-dilation result from earlier.}$$