Days 2

Learning goals: · Algebra and geometry of systems of knuer equations · Intro to Gaussian elimination / row ruduction. NB Today, F=R. Example 1 Solve 3x+2y=5 Solin Eliminate variables. Multiphy second eq'n by 2 thin add eq'ns to eliminate y: 3x + 2y = 53x + 2y = 5+ 4x - 2y = 2 $7x = 7 \implies x = l,$ Substitute x=1 into first egin to get 3+2y=5 => y=1 So the unique solin is x=y=1.

Geometric pictura: /2x - y = 1..... solution: (1,1)3x + 2y = 5Think Pair - Share (TPS) What vectors are perpendicular to the line goven by 3x+2y=5? What about 2x-y=1? How are thus related to the eq'ns? Example 2 System -9x - 3y = 6 (1) 3x + y = -2, (2)

Since (1) is a scalar multiple of (2), they have the same solins: {(x,y) y=-3x-2}

Geometry:

3x + y = -2

Example 3 System: -9x - 3y = 63x + y = -1Dividing first eq'n by -3, get 3x + y = -2. Thus no $(x, y) \in \mathbb{R}^2$ satisfies both eq'ns. Geometry: 3x + y = -2 3x + y = -1parallel lines (same perpendicular vectors too ?) Example 4 (Gaussian elimination) System: x+ 2y + z = 0 x +7 =4 x + y +22 = 1 Idea: Replace this system with a system having the same set of solutions which, moreover, are wident from the form of

the system. same set of solins Create "equivalent systems" via row operations: (') Multiply an eq'n by a nonzero scalar. (2) Swap two egins (3) Add a multiple of one eg'n to another. Pause Convince purself that the solution set is invariant under this operations, In implementing these operations, it's nice to have a shorthand for systems: $\underset{1}{\overset{1}{\longrightarrow}} \begin{pmatrix} 1 & 2 & 1 & 0 \\ 1 & 0 & 1 & 4 \\ 1 & 1 & 2 & 1 \end{pmatrix}$ x + 2y + z = 0x +z =4 x + y +2z = 1 augmented matrix: just record the coefficients! Let r:= i-th row of the augmented matrix. eliminate x from Observe $\begin{pmatrix} 1 & 2 & 1 & 0 \\ 1 & 0 & 1 & 4 \\ 1 & 1 & 2 & 1 \end{pmatrix} \xrightarrow{r_2 \to r_2 \to r_1} \begin{pmatrix} 1 & 2 & 1 & 0 \\ 0 & -2 & 0 & 4 \\ \hline r_3 \to r_3 - r_1 & 0 & -1 & 1 \end{pmatrix}$

 $\begin{array}{c} r_{2} \rightarrow -\frac{1}{2}r_{2} \\ \hline \\ -\frac{1}{2}r_{2} \\ \hline \\ 0 \\ 1 \\ 2 \\ -2 \\ \end{array} \begin{pmatrix} 1 & 2 & 1 & | 0 \\ 0 \\ 1 & 0 \\ -2 \\ 0 \\ -1 \\ 1 \\ 1 \\ \end{array} \begin{pmatrix} r_{3} \rightarrow r_{3} + r_{2} \\ 0 \\ -2 \\ 0 \\ 0 \\ 1 \\ -2 \\ 0 \\ 0 \\ 1 \\ -1 \\ \end{array} \begin{pmatrix} 1 & 2 & 1 & | 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ -2 \\ 0 \\ 0 \\ 1 \\ -1 \\ \end{array} \end{pmatrix}$ eliminate y from 3 z=-1 $r_{1} \rightarrow -2r_{2} + r_{1} \begin{pmatrix} 1 & 0 & 1 & -4 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 0 & -2 \\ 0 & 0 & 1 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 & 0 & 5 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & -1 \end{pmatrix}$ liminate y from 1 liminateWe learn that the unique solution (x, y, z) = (5, -2, -1). Pause Check that this is a sol'n to the original system ! Erample 5 System: x + 2y + z = 0x + 7 = 4 x + y + = 1 Sime as pravious, but this was 22

Parforming a similar sequence of row opins, get corresponding to x=4 7=-2 0 = -1 2 9 Upshot: NO solins to this (monimalist skull and crossbonks := system contradiction] Example 6 Another small modification : x + 2y + z = 0x + 7 = 4x + 7 + 2 = 2same as previous but $1 \rightarrow 2$. Gaussian reduction: $\begin{pmatrix}
1 & 2 & 1 & 0 \\
1 & 0 & 1 & 4 \\
1 & 1 & 1 & 2
\end{pmatrix}
\xrightarrow{(1 & 0 & 1 & | & 4 \\
0 & 1 & 0 & | & -2 \\
0 & 0 & 0 & | & 0
\end{pmatrix}$

corresponding to x+z=4 y=-2 0=D

Thus get infinite solution set

 $\{(x,y,z) \in \mathbb{R}^3 | x+z=4, y=-2\}$

 $= \{(x, -2, 4-x) | x \in \mathbb{R}\},\$

a line in R³.

NB Each "row reduction" today ended in "reduced echelon form." We will (a) define this precisely, (b) prove that the Gaussian ruduction algor than always regults in this form, (c) understand solution sets from this form.