

Problem 1

Problem Set 4

Write:  $f(x) = \underbrace{\frac{1}{2}(f(x) + f(-x))}_{= f_+(x)} + \underbrace{\frac{1}{2}(f(x) - f(-x))}_{= f_-(x)} = f_+(x) + f_-(x)$

we have  $\hat{\Pi} f_+(x) = \frac{1}{2}(f(-x) + f(x)) = f_+(x)$

$\hat{\Pi} f_-(x) = \frac{1}{2}(f(-x) - f(x)) = -f_-(x)$

so  $f_+(x)$  &  $f_-(x)$  are eigenfunctions of the parity operator.

Problem 2

Using  $\hat{R}_z = e^{-i\phi/\hbar \hat{L}_z} \approx (1 - i\phi/\hbar \hat{L}_z)$ , we have:

$\hat{L} \hat{R}_z = (1 + i\phi/\hbar \hat{L}_z) \hat{L} (1 - i\phi/\hbar \hat{L}_z)$   
 $= \hat{L} + i\phi/\hbar [\hat{L}_z, \hat{L}] + O(\phi^2)$

We know that  $[\hat{L}_z, \hat{L}_j] = i\hbar \epsilon_{zjk} \hat{L}_k$  so for  $j=z: [\hat{L}_z, \hat{L}_y] = i\hbar \hat{L}_x$   
 &  $[\hat{L}_z, \hat{L}_x] = i\hbar \hat{L}_y$

$\hat{L}_x = \hat{L}_x - \phi \hat{L}_y$ ,  $\hat{L}_y = \hat{L}_y + \phi \hat{L}_x$ ,  $\hat{L}_z = \hat{L}_z$  (inf. rot. about  $z$ )

$\hat{L}$  transforms like a vector under rotations.

Problem 3 (6.13)

a.  $\hat{p}_z$  is a vector operator, &  $\langle 100 | \hat{p}_z | 100 \rangle = 0$  since  $l'=0, l=0$  &  $l+l'$  is "even" (Laporte's rule).

b. we need to pick 2 states w/  $l'+l$  odd, try:  $\langle 210 | \hat{p}_z | 200 \rangle$

working in position space:

$\psi_{200} = \sqrt{\frac{1}{a^3 \cdot 8}} e^{-r/a} L_1^1(r/a) Y_0^0(\theta, \phi) = \frac{e^{-r/a}}{\sqrt{32\pi a^3}} (2 - r/a)$   
 (4.89)

$\psi_{210} = \sqrt{\frac{1}{a^3 \cdot 24}} e^{-r/a} \frac{r}{a} L_0^2(r/a) Y_1^0(\theta, \phi) = \frac{e^{-r/a} (r/a)}{\sqrt{24} a^2} \left(\frac{3}{4\pi}\right)^{1/2} \cos\theta$

use  $\vec{r} = r \sin\theta \cos\phi \hat{x} + r \sin\theta \sin\phi \hat{y} + r \cos\theta \hat{z}$

$\langle 210 | \hat{p}_z | 200 \rangle = \int_0^\infty \int_0^{2\pi} \int_0^\pi \psi_{210}^* \hat{p}_z \psi_{200} r^2 \sin\theta d\theta d\phi dr$  - the  $\hat{x} + \hat{y}$  components go away via  $\int_0^{2\pi} \dots d\phi = 0$

$= \frac{1}{16a^4} \int_0^\infty \int_0^\pi e^{-r/a} r^4 (2 - r/a) \cos^2\theta \sin\theta d\theta dr \cdot \int_0^\pi \cos^2\theta \sin\theta d\theta = 2/3$   
 $= -72a^6$

$= \frac{2}{24a^4} \int_0^\infty e^{-r/a} (2 - r/a) r^4 dr = -3a \hat{z}$

### Problem 4 (6.19)

For:  $[\hat{L}_i, \hat{V}_j] = i\hbar \epsilon_{ijk} \hat{V}_k$ , we have non-zero commutators:

$$[\hat{L}_x, \hat{V}_y] = i\hbar \hat{V}_z \quad [\hat{L}_x, \hat{V}_z] = -i\hbar \hat{V}_y$$

$$[\hat{L}_y, \hat{V}_x] = -i\hbar \hat{V}_z \quad [\hat{L}_y, \hat{V}_z] = i\hbar \hat{V}_x$$

$$[\hat{L}_z, \hat{V}_x] = i\hbar \hat{V}_y \quad [\hat{L}_z, \hat{V}_y] = -i\hbar \hat{V}_x$$

a.  $[\hat{L}_z, \hat{V}_\pm] = [\hat{L}_z, \hat{V}_x \pm i\hat{V}_y] = i\hbar \hat{V}_y \pm \hbar \hat{V}_x = \pm \hbar (\hat{V}_x \pm i\hat{V}_y) = \pm \hbar \hat{V}_\pm$

In order to get  $\hat{L}^2 = \hat{L}_x^2 + \hat{L}_y^2 + \hat{L}_z^2$  commutators, we'll use  $[A, B] = C \Rightarrow [A^2, B] = AC + CA$  so we need:

$$[\hat{L}_x^2, \hat{V}_\pm] = [\hat{L}_x, \hat{V}_x \pm i\hat{V}_y] = \mp \hbar \hat{V}_z$$

$$[\hat{L}_y^2, \hat{V}_\pm] = [\hat{L}_y, \hat{V}_x \pm i\hat{V}_y] = -i\hbar \hat{V}_z$$

and then:

$$[\hat{L}_x^2, \hat{V}_\pm] = \mp \hbar (\hat{L}_x \hat{V}_z + \hat{V}_z \hat{L}_x) = \mp \hbar (2\hat{V}_z \hat{L}_x - i\hbar \hat{V}_y) = \mp 2\hbar \hat{V}_z \hat{L}_x \pm i\hbar^2 \hat{V}_y$$

$$[\hat{L}_y^2, \hat{V}_\pm] = -i\hbar (\hat{L}_y \hat{V}_z + \hat{V}_z \hat{L}_y) = -i\hbar (2\hat{V}_z \hat{L}_y + i\hbar \hat{V}_x) = -2i\hbar \hat{V}_z \hat{L}_y + \hbar^2 \hat{V}_x$$

$$[\hat{L}_z^2, \hat{V}_\pm] = \pm \hbar (\hat{L}_z \hat{V}_\pm + \hat{V}_\pm \hat{L}_z) = \pm \hbar (2\hat{V}_\pm \hat{L}_z \pm \hbar \hat{V}_\pm) = \pm 2\hbar \hat{V}_\pm \hat{L}_z + \hbar^2 \hat{V}_\pm$$

so:  $[\hat{L}^2, \hat{V}_\pm] = [\hat{L}_x^2, \hat{V}_\pm] + [\hat{L}_y^2, \hat{V}_\pm] + [\hat{L}_z^2, \hat{V}_\pm]$  is

$$\begin{aligned} [\hat{L}^2, \hat{V}_\pm] &= \mp 2\hbar \hat{V}_z \hat{L}_x \pm i\hbar^2 \hat{V}_y - 2i\hbar \hat{V}_z \hat{L}_y + \hbar^2 \hat{V}_x \pm 2\hbar \hat{V}_\pm \hat{L}_z + \hbar^2 \hat{V}_\pm \\ &= \mp 2\hbar \hat{V}_z (\hat{L}_x \pm i\hat{L}_y) + \hbar^2 (\hat{V}_x \pm i\hat{V}_y) = \mp 2\hbar \hat{V}_z \hat{L}_\pm + \hbar^2 \hat{V}_\pm \\ &= \mp 2\hbar \hat{V}_z \hat{L}_\pm + \hbar^2 \hat{V}_\pm \pm 2\hbar \hat{V}_\pm \hat{L}_z \end{aligned}$$

b. We are given:  $\hat{L}^2 |\psi\rangle = \hbar^2 \ell(\ell+1) |\psi\rangle \rightarrow \hat{L}_z |\psi\rangle = \hbar \ell |\psi\rangle$  (top rung)  
we want to evaluate the state:  $\hat{V}_+ |\psi\rangle$ :

$$\begin{aligned} \hat{L}^2 \hat{V}_+ |\psi\rangle &= (\hat{V}_+ \hat{L}^2 - 2\hbar \hat{V}_z \hat{L}_+ + 2\hbar^2 \hat{V}_+ + 2\hbar \hat{V}_+ \hat{L}_z) |\psi\rangle \text{ using the commutator from part a.} \\ &= \hbar^2 \ell(\ell+1) \hat{V}_+ |\psi\rangle - 2\hbar \hat{V}_z \hat{L}_+ |\psi\rangle + 2\hbar^2 \hat{V}_+ |\psi\rangle + 2\hbar^2 \ell \hat{V}_+ |\psi\rangle \\ &= \hbar^2 (\ell(\ell+1) + 2(\ell+1)) \hat{V}_+ |\psi\rangle \stackrel{m=\ell}{=} \hbar^2 (\ell+2)(\ell+1) \hat{V}_+ |\psi\rangle \end{aligned}$$

so  $\hat{L}^2 \hat{V}_+ |\psi\rangle = \hbar^2 (\ell+2)(\ell+1) \hat{V}_+ |\psi\rangle \rightarrow \hat{V}_+ |\psi\rangle$  is an e-state of  $\hat{L}^2$  w/ eval  $\hbar^2 (\ell+2)(\ell+1)$  (or  $\hat{V}_+ |\psi\rangle = 0$ ). - now check  $\hat{L}_z$ :

$$\hat{L}_z \hat{V}_+ |\psi\rangle = (\hat{V}_+ \hat{L}_z + \hbar \hat{V}_+) |\psi\rangle = \hbar (\ell+1) \hat{V}_+ |\psi\rangle \text{ using the other commutator from part a.}$$

$\hat{V}_+ |\psi\rangle$  is an eystate of  $\hat{L}_z$  w/ eval  $\hbar(\ell+1)$  (or  $\hat{V}_+ |\psi\rangle = 0$ )

### Problem 5 (6.220)

We had:  $[\hat{L}_x, \hat{V}_y] = i\hbar \hat{V}_z$   $[\hat{L}_x, \hat{V}_z] = -i\hbar \hat{V}_y$  from  $[\hat{L}_i, \hat{V}_j] = i\hbar \epsilon_{ijk} \hat{L}_k$   
 $[\hat{L}_y, \hat{V}_x] = -i\hbar \hat{V}_z$   $[\hat{L}_y, \hat{V}_z] = i\hbar \hat{V}_x$   
 $[\hat{L}_z, \hat{V}_x] = i\hbar \hat{V}_y$   $[\hat{L}_z, \hat{V}_y] = -i\hbar \hat{V}_x$

(6.50):  $[\hat{L}_z, \hat{V}_z] = i\hbar \epsilon_{zjk} \hat{L}_k = 0$

(6.51): done in previous problem.

(6.52):  $[\hat{L}_\pm, \hat{V}_\pm] = [\hat{L}_x \pm i\hat{L}_y, \hat{V}_x \pm i\hat{V}_y]$   
 $= [\hat{L}_x, \hat{V}_x] \pm i[\hat{L}_x, \hat{V}_y] \pm i[\hat{L}_y, \hat{V}_x] \mp [\hat{L}_y, \hat{V}_y]$   
 $= \mp \hbar \hat{V}_z \pm \hbar \hat{V}_z = 0$

(6.53):  $[\hat{L}_\pm, \hat{V}_z] = [\hat{L}_x \pm i\hat{L}_y, \hat{V}_z] = [\hat{L}_x, \hat{V}_z] \pm i[\hat{L}_y, \hat{V}_z] = -i\hbar \hat{V}_y \pm i(i\hbar \hat{V}_x)$   
 $= \mp \hbar (\hat{V}_x \pm i\hat{V}_y) = \mp \hbar \hat{V}_\pm$

(6.54):  $[\hat{L}_\pm, \hat{V}_\pm] = [\hat{L}_x \pm i\hat{L}_y, \hat{V}_x \pm i\hat{V}_y] = \pm i([\hat{L}_x, \hat{V}_y] \mp [\hat{L}_y, \hat{V}_x])$   
 $= \pm i(i\hbar \hat{V}_z - i\hbar \hat{V}_z) = 0$

### Problem 6 (6.18)

a. Working w/ a test function:  $[\hat{T}, \hat{\Pi}] f(x) = \hat{T} \hat{\Pi} f(x) - \hat{\Pi} \hat{T} f(x)$   
 $= \hat{T} f(-x) - \hat{\Pi} f(x-a)$   
 $= f(-x-a) - f(-x+a) \neq 0$

b. For  $f_p(x) = \frac{1}{\sqrt{2\pi\hbar}} e^{ipx/\hbar}$ , we have:  $\hat{\Pi} f_p(x) = \frac{1}{\sqrt{2\pi\hbar}} e^{-ipx/\hbar} = \frac{1}{\sqrt{2\pi\hbar}} e^{i(-p)x/\hbar} = f_{-p}(x)$

c.  $\hat{T}(a) \left[ \frac{1}{\sqrt{\pi\hbar}} \cos\left(\frac{px}{\hbar}\right) \right] = \frac{1}{\sqrt{\pi\hbar}} \cos\left(\frac{p(x-a)}{\hbar}\right) = \frac{1}{\sqrt{\pi\hbar}} \left( \cos\left(\frac{px}{\hbar}\right) \cos\left(\frac{pa}{\hbar}\right) + \sin\left(\frac{px}{\hbar}\right) \sin\left(\frac{pa}{\hbar}\right) \right)$

+

$\hat{T}(a) \left[ \frac{1}{\sqrt{\pi\hbar}} \sin\left(\frac{px}{\hbar}\right) \right] = \frac{1}{\sqrt{\pi\hbar}} \sin\left(\frac{p(x-a)}{\hbar}\right) = \frac{1}{\sqrt{\pi\hbar}} \left( \sin\left(\frac{px}{\hbar}\right) \cos\left(\frac{pa}{\hbar}\right) - \cos\left(\frac{px}{\hbar}\right) \sin\left(\frac{pa}{\hbar}\right) \right)$

## Problem 7

For  $i\hbar \frac{\partial \psi}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} + qV(t)\psi$  w/  $\psi(0,t) = 0 = \psi(a,t)$

Moving the time-dependent potential over to the left, & taking  $\psi(x,t) = X(x)T(t)$ :

$$i\hbar (\dot{T}X) - qV(t)TX = -\frac{\hbar^2}{2m} X''T \quad \text{divide by } XT \text{ to get:}$$

$$i\hbar \frac{\dot{T}}{T} - qV(t) = -\frac{\hbar^2}{2m} \frac{X''}{X}$$

Setting both sides equal to  $E$ , a constant, we get

$$-\frac{\hbar^2}{2m} \frac{X''}{X} = E \Rightarrow X(x) = \sqrt{\frac{2}{a}} \sin\left(\frac{n\pi x}{a}\right) \quad \text{w/ } E_n = \frac{\hbar^2 \pi^2 n^2}{2ma^2} \text{ as usual for the infinite sq. well.}$$

For the  $t$ -eqn:  $i\hbar \frac{\dot{T}}{T} - qV(t) = E \Rightarrow i\hbar \dot{T} = (E + qV(t))T$

or

$$\dot{T} = \frac{1}{i\hbar} (E + qV(t))T \quad \text{let } w(t) \equiv \frac{1}{i\hbar} (E + qV(t))$$

$$\dot{T} = w(t)T \quad (*)$$

Consider the function:  $T(t) = \alpha e^{u(t)}$  for some  $u(t)$  - what is the relation between  $u(t)$  &  $w(t)$ ? Putting  $\uparrow$  into  $(*)$

$$\dot{T} = \alpha \dot{u} e^u = wT = w \alpha e^u \Rightarrow \dot{u} = w \Rightarrow u(t) = \int_0^t w(\bar{t}) d\bar{t}$$

$$\begin{aligned} \text{So } T(t) &= \alpha e^{\int_0^t w(\bar{t}) d\bar{t}} = \alpha e^{\int_0^t \frac{1}{i\hbar} (E + qV(\bar{t})) d\bar{t}} \\ &= \alpha e^{-iE t/\hbar} \cdot e^{-i/\hbar \int_0^t qV(\bar{t}) d\bar{t}} \end{aligned}$$

The solution for  $\psi(x,t)$  is: (adding up all the  $E_n$  contributors)

$$\psi(x,t) = \sum_{j=1}^{\infty} c_j e^{-iE_j t/\hbar} \cdot e^{-i/\hbar \int_0^t qV(\bar{t}) d\bar{t}} \cdot \sqrt{\frac{2}{a}} \sin\left(\frac{j\pi x}{a}\right)$$

$$= e^{-i/\hbar \int_0^t qV(\bar{t}) d\bar{t}} \underbrace{\sum_{j=1}^{\infty} c_j e^{-iE_j t/\hbar} \sqrt{\frac{2}{a}} \sin\left(\frac{j\pi x}{a}\right)}_{\equiv \bar{\psi}(x,t)}$$

$$\psi(x,t) = \underbrace{e^{-i/\hbar \int_0^t qV(\bar{t}) d\bar{t}}}_{\text{undetectable, time-varying, pure phase}} \bar{\psi}(x,t)$$