

Problem 1

Problem Set 2

$$e^{iA} = \sum_{j=0}^{\infty} \frac{1}{j!} (iA)^j \quad \text{for } A = V D V^+, A^2 = V D V^+ V D V^+ = V D^2 V^+ = II$$

+ then  $A^2 = V D^2 V^+$ , so

$$= V \left[ \sum_{j=0}^{\infty} \frac{1}{j!} (iD)^j \right] V^+ = V e^{iD} V^+ \quad \begin{pmatrix} e^{i\lambda_1} \\ e^{i\lambda_2} \\ \vdots \\ e^{i\lambda_n} \end{pmatrix}$$

Then for  $U = e^{iA} = V e^{iD} V^+$ , we have

$$U^+ = (V e^{iD} V^+)^+ = V e^{-iD} V^+ = V \left[ \sum_{j=0}^{\infty} \frac{1}{j!} (-iD)^j \right] V^+ = e^{-iA}$$

$\begin{pmatrix} e^{-i\lambda_1} \\ e^{-i\lambda_2} \\ \vdots \\ e^{-i\lambda_n} \end{pmatrix}$

$$\text{and } U^+ U = V e^{-iD} V^+ V e^{iD} V^+ = V \underbrace{e^{-iD} e^{iD}}_{=II} V^+ = V V^+ = II$$

Problem 2

The eigenvalue problem for  $L_2$ :  $L_2 V = V D$  has:  $D = \begin{pmatrix} i & 0 & 0 \\ 0 & -i & 0 \\ 0 & 0 & 0 \end{pmatrix}$

$$\text{so } V = \begin{pmatrix} i & -i & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \text{ then } L_2 = V D V^{-1}, \quad V^{-1} = \begin{pmatrix} -i & i & 0 \\ i & i & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

As in the first problem, we have:  $L_2^{-1} = V D^{-1} V^{-1}$ , so that

$$e^{\theta L_2} = \sum_{j=0}^{\infty} \frac{(i\theta L_2)^j}{j!} = V \left[ \sum_{j=0}^{\infty} \frac{1}{j!} (i\theta D)^j \right] V^{-1} = V e^{\theta D} V^{-1}$$

$$\text{while } e^{\theta D} = \begin{pmatrix} e^{i\theta} & 0 & 0 \\ 0 & e^{-i\theta} & 0 \\ 0 & 0 & 1 \end{pmatrix}, \text{ so } e^{\theta L_2} = V e^{\theta D} V^{-1} = \begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Problem 3

$$a. -\frac{\hbar^2}{2m} \nabla^2 \psi + U\psi = i\hbar \frac{d\psi}{dt} \Rightarrow \frac{d\psi}{dt} = \frac{1}{i\hbar} \left[ -\frac{\hbar^2}{2m} \nabla^2 \psi + U\psi \right] + \frac{d\psi^*}{dt} = -\frac{1}{i\hbar} \left[ -\frac{\hbar^2}{2m} \nabla^2 \psi^* + U\psi^* \right]$$

$$\begin{aligned} \text{Now, } \frac{d}{dt} \int_{\Omega} \psi^* \psi d\tau &= \int_{\Omega} \left[ \frac{d\psi^*}{dt} \psi + \psi^* \frac{d\psi}{dt} \right] d\tau \\ &= \int_{\Omega} \left\{ -\frac{1}{i\hbar} \left[ -\frac{\hbar^2}{2m} \nabla^2 \psi^* \psi + U\psi^* \psi \right] + \frac{1}{i\hbar} \left[ -\frac{\hbar^2}{2m} \nabla^2 \psi \psi^* + U\psi^* \psi \right] \right\} d\tau \\ &= \frac{1}{i\hbar} \int_{\Omega} \left[ \frac{\hbar^2}{2m} \nabla^2 \psi^* \psi - \frac{\hbar^2}{2m} \nabla^2 \psi \psi^* \right] d\tau \quad (*) \end{aligned}$$

Note that:  $\int_{\Omega} \nabla \cdot (\nabla \psi^* \psi) d\tau = \int_{\partial\Omega} (\nabla \psi^* \cdot \vec{n}) \psi d\vec{s}$  by the div. thm.  
 " (product rule)

$$\int_{\Omega} [\nabla^2 \psi^* \psi + \nabla \psi^* \cdot \nabla \psi] d\tau = \int_{\partial\Omega} [\nabla \psi^* \psi] \cdot d\vec{s}$$

$$\text{Hence } \int_{\Omega} \nabla^2 \psi^* \psi d\tau = - \int_{\Omega} \nabla \psi^* \cdot \nabla \psi d\tau - \int_{\partial\Omega} [\nabla \psi^* \psi] \cdot d\vec{s}$$

$$\text{Also, } \int_{\Omega} \nabla^2 \psi \psi^* d\tau = - \int_{\Omega} \nabla \psi \cdot \nabla \psi^* d\tau + \int_{\partial\Omega} [\nabla \psi \psi^*] \cdot d\vec{s}$$

Using these back in (\*),

$$\frac{d}{dt} \int_{\Omega} \psi^* \psi d\tau = \frac{\hbar}{i2m} \int_{\partial\Omega} [4\nabla \psi^* \psi - \psi^* \nabla \psi] \cdot d\vec{s}$$

$$\therefore \vec{J} = -\frac{\hbar}{2mi} (\psi \nabla \psi^* - \psi^* \nabla \psi)$$

- b. If  $\Omega$  is all space,  $-\int_{\Omega} \vec{J} \cdot d\vec{s} = 0$  since  $\psi \rightarrow 0$  as  $r \rightarrow \infty$ , where the integral is evaluated.

Problem 4

$$\text{For } \psi = Re^{is}, \quad \frac{\partial \psi}{\partial t} = Re^{is} + isRe^{is} = \left(\frac{R}{m} + is\right)\psi$$

$$+ \nabla \psi = \nabla Re^{is} + Re^{is}\nabla s \quad \nabla^* \psi = \nabla Re^{-is} - Re^{-is}\nabla s$$

$$\nabla^2 \psi = \nabla^2 Re^{is} + i\nabla R \cdot \nabla s e^{is} + i\nabla R \cdot \nabla s e^{is} + i\nabla^2 s Re^{is} - R \nabla s \cdot \nabla s e^{is}$$

$$= \left[ \frac{\nabla^2 R}{m} + i \left( \frac{\nabla R \cdot \nabla s}{m} + \nabla^2 s \right) - \nabla s \cdot \nabla s \right] \psi$$

then  $-\frac{k^2}{2m} \nabla^2 \psi + U\psi = ik \frac{\partial \psi}{\partial t}$  becomes

$$-\frac{k^2}{2m} \left[ \frac{\nabla^2 R}{m} + i \left( 2 \frac{\nabla R \cdot \nabla s}{m} + \nabla^2 s \right) - \nabla s \cdot \nabla s \right] \psi + U\psi = \left( \frac{ikR}{m} - ks \right) \psi$$

the real part of this eqn. is:

$$-\frac{k^2}{2m} \left[ \frac{\nabla^2 R}{m} - \nabla s \cdot \nabla s \right] \psi + U = -ks$$

$$\text{w/ imaginary part: } -\frac{k^2}{2m} \left[ \frac{2\nabla R \cdot \nabla s}{m} + \nabla^2 s \right] = k \frac{R}{m}$$

The probability density is.  $\rho = \psi^* \psi = R^2$

$$\begin{aligned} \vec{J} &= K [\psi \nabla \psi^* - \psi^* \nabla \psi] \\ &= K [Re^{is} (\nabla Re^{-is} - Re^{-is} \nabla s) - Re^{is} (\nabla Re^{is} + Re^{is} i \nabla s)] \\ &= K [R \nabla R - i R^2 \nabla s - R \nabla R - i R^2 \nabla s] \\ &= -2iKR^2 \nabla s \quad \text{w/ } K = \frac{ik}{2m} \\ \vec{J} &= \frac{ik}{m} R^2 \nabla s \end{aligned}$$

### Problem 5

We have  $\frac{d\hat{J}}{dt} = \{\hat{J}, \hat{H}\}$  for functions  $J \in H$ . The rule to get QM op. is  $\{, \} \rightarrow \frac{i\hbar}{m} [\cdot, \cdot]$ , so it's  $\frac{d\hat{J}}{dt} = [\hat{J}, \hat{H}]$ .

→ taking the expectation value of both sides,

$$\frac{d\langle \hat{J} \rangle}{dt} = \frac{1}{i\hbar} \langle [\hat{J}, \hat{H}] \rangle.$$

### Problem 6

Taking  $\hat{I} = \vec{r}$ , we need to compute:  $[\vec{r}, \hat{H}]$  w/

$$\hat{H} = (\vec{p}^2 - q\vec{p} \cdot \vec{A} - q\vec{A} \cdot \vec{p} + q^2 A^2) \cdot \frac{1}{2m}$$

the first commutator is (take the  $x$ -component to get the pattern)

$$[x, p_x^2 + p_y^2 + p_z^2] = [x, p_x^2] = x p_x p_x - p_x p_x x = (ix + p_x x) p_x - p_x (xp_x - ik) = 2ik p_x$$

$$\text{so } [y, p^2] = 2ik p_y, [z, p^2] = 2ik p_z$$

$$[x, p_x A_x + p_y A_y + p_z A_z] = [x, p_x A_x] = x p_x A_x - p_x A_x x = (p_x x + ik) A_x - p_x x A_x = ik A_x$$

$$\text{w/ } [y, \vec{p} \cdot \vec{A}] = ik A_y, [z, \vec{p} \cdot \vec{A}] = ik A_z$$

Now we have:

$$[x, A_x p_x + A_y p_y + A_z p_z] = [x, A_x p_x] = x A_x p_x - A_x p_x x = A_x x p_x - A_x (xp_x - ik) = ik A_x$$

$$\text{w/ } [y, \vec{A} \cdot \vec{p}] = ik A_y, [z, \vec{A} \cdot \vec{p}] = ik A_z.$$

$$\begin{aligned} \text{Then: } [x, \hat{H}] &= \frac{1}{2m} \left( [x, p^2] - q[x, \vec{p} \cdot \vec{A}] - q[x, \vec{A} \cdot \vec{p}] + q^2 [x, A^2] \right) \\ &= \frac{1}{2m} (2ik p_x - 2ik q A_x) = ik \frac{1}{m} (p_x - q A_x) \end{aligned}$$

$$\rightarrow [\vec{r}, \hat{H}] = ik \frac{1}{m} (\vec{p} - q \vec{A})$$

Ehrenfest's theorem says:  $\frac{d\langle \vec{r} \rangle}{dt} = \frac{1}{i\hbar} \langle [\vec{r}, \hat{H}] \rangle$

$$\frac{d\langle \vec{r} \rangle}{dt} = \frac{1}{m} \langle \vec{p} - q \vec{A} \rangle \quad \checkmark$$