

## Problem 2 (11.12)

## Problem Set 5

Using the Larmor power:  $P = \frac{\mu_0 q^2 \dot{a}^2}{6\pi\epsilon_0 c^3}$  w/  $a = g = 9.8 \text{ m/s}^2$  (so that  $P$  is constant)  
 We have:  $\Delta U = P \cdot \Delta t$ , w/  $d = \frac{1}{2} g \Delta t^2 \Rightarrow U = P \cdot \sqrt{\frac{2d}{g}}$

Setting  $d = .01 \text{ m}$ ,  $q = 1.6 \times 10^{-19} \text{ C}$ ,  $c = 3 \times 10^8 \text{ m/s}$  &  $\mu_0 = 4\pi \times 10^{-7} \text{ N/A}^2$ , we have  
 $\Delta U = 2.47 \times 10^{-58} \text{ J}$

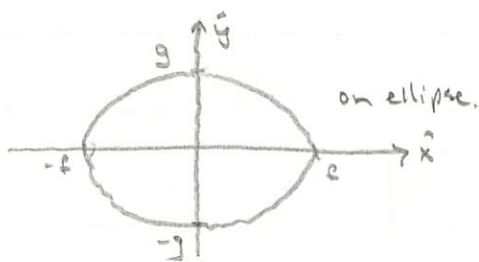
The initial potential energy is:  $W = mgd$  w/  $m = 9.11 \times 10^{-31} \text{ kg}$ ,  $W \approx 8.93 \times 10^{-32} \text{ J}$   
 so  $\frac{\Delta U}{W} = 2.77 \times 10^{-22}$  (very little)

## Problem 3

$\vec{w}(t) = f \cos(\omega t) \hat{x} + g \sin(\omega t) \hat{y}$ , sketch:

$\vec{a}(t) = \ddot{\vec{w}}(t) = -\omega^2 (f \cos(\omega t) \hat{x} + g \sin(\omega t) \hat{y})$

w/  $a^2 = \omega^4 (f^2 \cos^2(\omega t) + g^2 \sin^2(\omega t))$



so the time-averaged Larmor-Power is:

$$\langle P \rangle = \frac{\mu_0 q^2}{6\pi\epsilon_0 c^3} \langle a^2 \rangle = \frac{\mu_0 q^2 \omega^4 (f^2 + g^2)}{12\pi\epsilon_0 c^3}$$

for a circular trajectory:  $\langle P_0 \rangle = \frac{\mu_0 q^2 \omega^4 f^2}{6\pi\epsilon_0 c^3}$   
 (where  $g=f$ )

for the line trajectory ( $g=0$ ):  $\langle P_1 \rangle = \frac{\mu_0 q^2 \omega^4 f^2}{12\pi\epsilon_0 c^3}$  so  $\langle P_0 \rangle = 2 \langle P_1 \rangle$ , the circle radiates more.  
 $\frac{\langle P_0 \rangle}{\langle P_1 \rangle} = 2$

## Problem 4

$\vec{r}(t) = r_0 (\cos(\omega t) \hat{x} + \sin(\omega t) \hat{y}) \Rightarrow \ddot{\vec{r}}(t) = -\omega^2 r_0 (\cos(\omega t) \hat{x} + \sin(\omega t) \hat{y})$   
 $\hat{x} = \sin\theta \cos\phi \hat{r} + \cos\theta \cos\phi \hat{\theta} - \sin\phi \hat{\phi}$ ,  $\hat{y} = \sin\theta \sin\phi \hat{r} + \cos\theta \sin\phi \hat{\theta} + \cos\phi \hat{\phi}$

w/  $\hat{r} \times \hat{x} = \cos\theta \cos\phi \hat{\phi} + \sin\phi \hat{\theta}$ ,  $\hat{r} \times \hat{y} = \cos\theta \sin\phi \hat{\phi} - \cos\phi \hat{\theta}$

so  $\vec{B}(\vec{r}, t) = +\frac{\mu_0}{4\pi\epsilon_0 c^3} \omega^2 r_0 [\cos(\omega t_0) \cos\theta \cos\phi \hat{\phi} + \cos(\omega t_0) \sin\phi \hat{\theta} + \sin(\omega t_0) \cos\theta \sin\phi \hat{\phi} - \sin(\omega t_0) \cos\phi \hat{\theta}]$

$t_0 = t - r/c$

$$= \frac{\mu_0 \omega^2 r_0}{4\pi\epsilon_0 c^3} [(\cos(\omega t_0) \sin\phi - \sin(\omega t_0) \cos\phi) \hat{\theta} + \cos\theta (\cos(\omega t_0) \cos\phi + \sin(\omega t_0) \sin\phi) \hat{\phi}]$$

$$= \frac{\mu_0 \omega^2 r_0}{4\pi\epsilon_0 c^3} [\sin(\phi - \omega t_0) \hat{\theta} + \cos\theta \cos(\phi - \omega t_0) \hat{\phi}]$$

Problem 4 (continued)

$$\vec{E}^{ret}(\vec{r}, t) = c \hat{r} \times \vec{B}^{ret}(\vec{r}, t)$$

$$= \frac{\mu_0 \omega^2 p_0}{4\pi r} \left[ \sin(\phi - \omega t_0) \hat{\phi} - \cos\theta \cos(\phi - \omega t_0) \hat{\theta} \right]$$

$$\vec{S}^{ret}(\vec{r}, t) = \frac{1}{\mu_0} \vec{E}^{ret}(\vec{r}, t) \times \vec{B}^{ret}(\vec{r}, t)$$

$$= \frac{\mu_0}{c} \left( \frac{\omega^2 p_0}{4\pi r} \right)^2 \left[ \sin^2(\phi - \omega t_0) + \cos^2\theta \cos^2(\phi - \omega t_0) \right] \hat{r}$$

Problem 5

$\vec{w}(t) = \sqrt{b^2 + (ct)^2} \hat{z}$  to find the retarded time at  $t=0$ ,  $\vec{r} = x\hat{x} + z\hat{z}$ , we have to solve:

$$c^2(t - t_r)^2 = x^2 + (z - \sqrt{b^2 + (ct_r)^2})^2 \quad \text{for } t_r:$$

$$c^2 t_r^2 = x^2 + z^2 - 2z\sqrt{b^2 + (ct_r)^2} + b^2 + c^2 t_r^2$$

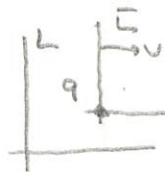
or  $\sqrt{b^2 + (ct_r)^2} = \frac{1}{2z}(x^2 + z^2 + b^2)$  squaring:

$$c^2 t_r^2 = \frac{1}{4z^2}(x^2 + z^2 + b^2)^2 - b^2$$

so  $t_r = \frac{1}{c} \left[ \frac{1}{4z^2}(x^2 + z^2 + b^2)^2 - b^2 \right]^{1/2}$   
 taking the - root so that  $t_r < t$

As  $z \rightarrow 0$ ,  $t_r \rightarrow -\infty$ .

Problem 6



In  $\bar{L}$ :  $\bar{\rho} = q \delta(\bar{x}) \delta(\bar{y}) \delta(\bar{z})$

In  $L$ :  $\rho = q \delta(x - vt) \delta(y) \delta(z)$

we have  $\bar{x} = \gamma(x - vt)$ ,  $\bar{y} = y$ ,  $\bar{z} = z$ ,  $\bar{t} = \gamma(t - vx/c^2)$

$$\bar{\rho} = q \delta(\gamma(x - vt)) \delta(y) \delta(z) = \frac{1}{\gamma} q \delta(x - vt) \delta(y) \delta(z)$$

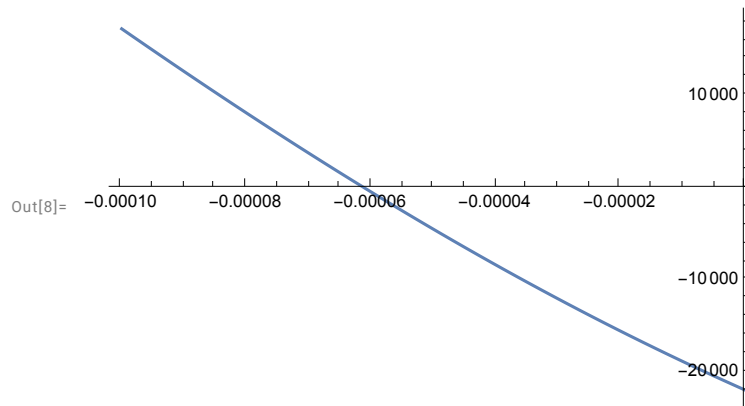
$\int \delta(\gamma u) = \frac{1}{|\gamma|} \delta(u)$

or  $\bar{\rho} = \frac{1}{\gamma} \rho \Rightarrow \rho = \gamma \bar{\rho}$ .

# Problem 1

## Part a.

```
In[1]:= w[t_] := d Cos[omega t] {0, 1, 0}
In[2]:= r = {d / 100, -d / 10, 0};
In[3]:= t = 0;
In[4]:= omega = 10 000;
          d = 20 000;
          c = 3 × 10^8;
In[7]:= F[p_] := c (t - p) - Sqrt[(r - w[p]).(r - w[p])]
In[8]:= Plot[F[p], {p, -10^(-4), 0}]
```



```
In[9]:= tr = p /. FindRoot[F[p], {p, 0.}][[1]]
Out[9]= -0.0000612268
```

At time  $t_r$ , the particle is at location:

```
In[10]:= w[tr]
Out[10]= {0., 16 366.9, 0.}
```

Very far from where it is at time 0:

```
In[11]:= w[0]
Out[11]= {0, 20 000, 0}
```

## Part b.

```
In[12]:= w[t_] := d Cos[omega t] {0, 1, 0}
```

```
In[13]:= r = {d / 100, -d / 10, 0};
```

```
In[14]:= t = 0;
```

```
In[15]:= omega = 30 000;
```

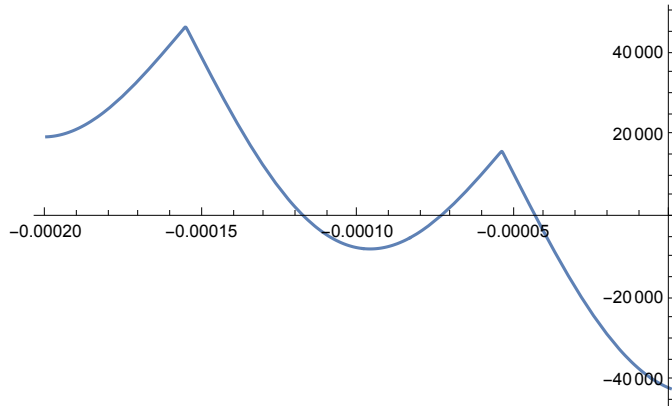
```
      d = 40 000;
```

```
      c = 3 × 10^8;
```

```
In[18]:= F[p_] := c (t - p) - Sqrt[(r - w[p]) . (r - w[p])]
```

```
In[19]:= Plot[F[p], {p, -.0002, 0}]
```

```
Out[19]=
```



The plot above has two roots, indicating that the particle achieves a speed greater than  $c$ :

```
In[20]:= omega d - c
```

```
Out[20]=
```

```
900 000 000
```

Indeed, the maximum speed of the particle is significantly greater than  $c$ . The three roots are

```
In[21]:= FindRoot[F[p], {p, -.00015}]
```

```
Out[21]=
```

```
{p → -0.000117294}
```

```
In[22]:= FindRoot[F[p], {p, -.0003}]
```

```
Out[22]=
```

```
{p → -0.0000740259}
```

```
In[23]:= FindRoot[F[p], {p, -.00005}]
```

```
Out[23]=
```

```
{p → -0.0000431282}
```