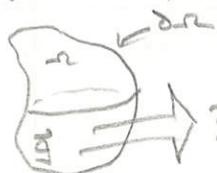


## Momentum Conservation

we suggested that fields might carry momentum,  
→ even found a candidate "field momentum  
density"

$$\vec{g} = \frac{1}{c^2} \vec{S} = \epsilon_0 \vec{E} \times \vec{B}$$

let's think about what conservation of field  
momentum might look like in an empty  
(of charges) region  $\Omega$ :



$$\frac{d}{dt} \int_{\Omega} \vec{g} dr = - \oint_{\partial\Omega} ? \cdot d\vec{a} \quad (*)$$

? is some sort of object that, when dotted into  
a vector ( $d\vec{a}$ ) returns a vector (the LHS of  
(\*) is a vector)

A matrix can be "dotted into a vector" returning  
a vector. Matrix vector multiplication says:

$$\vec{w} = A\vec{v} \text{ w/ } w^i = \sum_{j=1}^3 A^{ij} v^j \quad (i=1,2,3)$$

something written:  $\vec{w} = \overset{\leftrightarrow}{A} \cdot \vec{v}$

Last time we developed the combined particle-field

$$\frac{d\vec{w}}{dt} = - \frac{d}{dt} \int_{\Omega} u dr - \oint_{\partial\Omega} \vec{S} \cdot d\vec{a}$$

work done on the

charges in  $\Omega$  a statement of energy conservation

today we want to express the similar "momentum" conservation  
combining particles w/ fields:

$$\frac{d\vec{p}}{dt} = - \frac{d}{dt} \int_{\Omega} \vec{g} dr - \oint_{\partial\Omega} ? \cdot d\vec{a}$$

done in  
mechanical  
momentum

To start off take a domain  $\Omega$  w/ some individual  
charges



$$\text{the force on each charge is} \\ \vec{F} = q\vec{E} + q\vec{v} \times \vec{B}$$

moving to a continuum description:  $q \rightarrow \rho dr$

$$\vec{F} = \int_{\Omega} (\rho \vec{E} + \vec{p} \times \vec{B}) dr = \int_{\Omega} (\rho \vec{E} + \vec{J} \times \vec{B}) dr$$

w/ force density  $\vec{f} = \rho \vec{E} + \vec{J} \times \vec{B}$ . This  $\vec{F}$  is a  
good starting point since

$$\vec{F} = \frac{d\vec{p}}{dt} \text{ where } \vec{p} \text{ is the particle or} \\ \text{"mechanical" momentum,}$$

we'll open focus on  $\vec{p}$ , reflecting  $\rho \rightarrow \vec{p}$  w/ their  
expressions in terms of  $\vec{E} + \vec{B}$  & their various derivatives,

$$\vec{f} = \rho \vec{E} + \vec{J} \times \vec{B} \text{ w/ } \rho = \epsilon_0 \nabla \cdot \vec{E}, \quad \vec{J} = \frac{1}{\mu_0} \nabla \times \vec{B} - \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$= \epsilon_0 (\nabla \cdot \vec{E}) \vec{E} + \frac{1}{\mu_0} (\nabla \times \vec{B}) \times \vec{B} - \epsilon_0 \frac{\partial \vec{E}}{\partial t} \times \vec{B}$$

targeting familiar quantities, like  $\vec{E} \times \vec{B}$  ( $\sim \vec{S}$ )

$$\frac{\partial}{\partial t}(\vec{E} \times \vec{B}) = \vec{E} \times \frac{\partial \vec{B}}{\partial t} + \vec{B} \times \frac{\partial \vec{E}}{\partial t} \\ = -\nabla \times \vec{E}$$

so that:  $\frac{\partial \vec{E}}{\partial t} \times \vec{B} = \frac{\partial}{\partial t}(\vec{E} \times \vec{B}) + \vec{E} \times (\nabla \times \vec{E})$

giving

$$\vec{P} = \epsilon_0 [(\nabla \cdot \vec{E}) \vec{E} - \vec{E} \times (\nabla \times \vec{E})] + \frac{1}{\mu_0} [(\nabla \cdot \vec{B}) \vec{B} - \vec{B} \times (\nabla \times \vec{B})] - \epsilon_0 \frac{\partial}{\partial t}(\vec{E} \times \vec{B})$$

$= 0$ , add in for aesthetics

Finally, we can use the identity:

$$\vec{E} \times (\nabla \times \vec{E}) = \frac{1}{2} \nabla(E^2) - (\vec{E} \cdot \nabla) \vec{E}$$

to sum for  $\vec{B}$ :

$$\vec{P} = \epsilon_0 [(\nabla \cdot \vec{E}) \vec{E} + (\vec{E} \cdot \nabla) \vec{E} - \frac{1}{2} \nabla(E^2)] \quad \begin{matrix} \vec{E} \vec{B} \text{ momentum} \\ \text{density} \end{matrix} \\ + \frac{1}{\mu_0} [(\nabla \cdot \vec{B}) \vec{B} + (\vec{B} \cdot \nabla) \vec{B} - \frac{1}{2} \nabla(B^2)] - \frac{\partial}{\partial t}(\epsilon_0 \vec{E} \times \vec{B})$$

Define:  $T_{ij} = \epsilon_0 (E_i E_j - \frac{1}{2} \delta_{ij} E^2) + \frac{1}{\mu_0} (B_i B_j - \frac{1}{2} \delta_{ij} B^2)$

then  $\sum_{i=1}^3 \frac{\partial T_{ij}}{\partial x^i} = \sum_{i=1}^3 \epsilon_0 \left( \frac{\partial E_i}{\partial x^i} E_j + E_i \frac{\partial E_j}{\partial x^i} \right) - \frac{1}{2} \frac{\partial E^2}{\partial x^j} + \begin{matrix} \text{for } j=1, 2, 3 \\ \text{sym. for the } B \text{ terms} \end{matrix}$

$$\nabla \cdot \vec{T} = \epsilon_0 (\vec{E}(\nabla \cdot \vec{E}) + (\vec{E} \cdot \nabla) \vec{E} - \frac{1}{2} \nabla(E^2)) \\ + \frac{1}{\mu_0} (\vec{B}(\nabla \cdot \vec{B}) + (\vec{B} \cdot \nabla) \vec{B} - \frac{1}{2} \nabla(B^2)) \\ = \nabla \cdot \vec{T}$$

and we can write:

$$\vec{T} = -\nabla \cdot (-\vec{T}) - \frac{\partial}{\partial t} \vec{q}$$

+ going back to  $\frac{d\vec{T}}{dt} = \vec{F}$  w/  $\vec{F} = \int_{\Omega} \vec{T} d\tau$ ,

$$\frac{d\vec{T}}{dt} = - \int_{\Omega} \frac{\partial}{\partial t} \vec{q} d\tau - \int_{\Omega} \nabla \cdot (-\vec{T}) d\tau$$

$$= \frac{d}{dt} \int_{\Omega} \vec{q} d\tau - \int_{\partial\Omega} \vec{q} (-\vec{T}) \cdot \hat{n} \, ds. \quad (*)$$

the momentum analogue of

$$\frac{dW}{dt} = - \frac{d}{dt} \int_{\Omega} u d\tau - \int_{\partial\Omega} \vec{s} \cdot \hat{n} \, ds \quad (**)$$

for energy.

Note that  $\vec{s}$  appears as an energy current density in  $(**)$ , + or the conserved  $\vec{q} = \epsilon_0 \vec{S}$  in  $(*)$