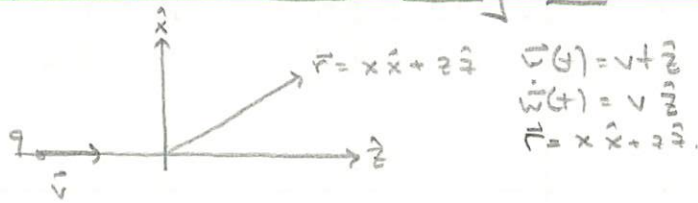


Potentials for Constant Velocity Motion



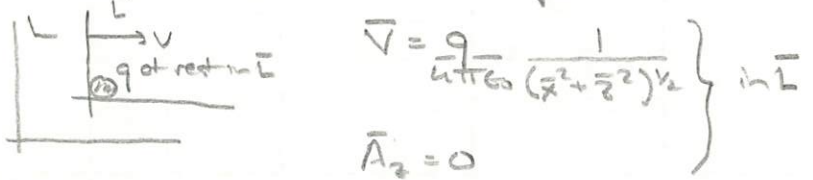
we thought about using $V(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{1}{(r - \vec{r} \cdot \vec{v}/c)}$

$\vec{r} = \vec{r} - \vec{w}(t_r)$ $\vec{A}(\vec{r}, t) = \frac{\mu_0 q}{4\pi} \frac{\vec{v}}{(r - \vec{r} \cdot \vec{v}/c)}$

$\vec{v} = \dot{\vec{w}}(t_r)$

$c(t - t_r) = |\vec{r} - \vec{w}(t_r)| \Rightarrow c^2(t - t_r)^2 = (x^2 + (z - vt_r)^2)$

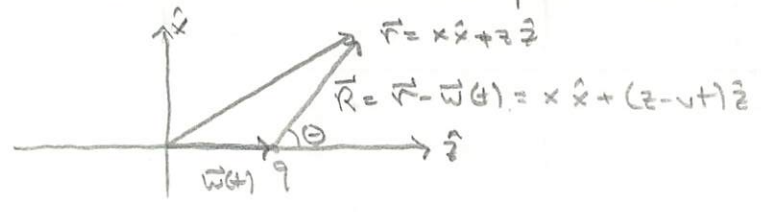
but decided to use our SR knowledge:



$\bar{L}: V = \gamma \bar{V}, A_z = \gamma v/c^2 \bar{V}$

$V = \frac{q}{4\pi\epsilon_0} \frac{1}{(x^2(1-v^2/c^2) + (z-vt)^2)^{1/2}}$ $\vec{A} = \frac{\mu_0 q}{4\pi} \frac{v \hat{z}}{(x^2(1-v^2/c^2) + (z-vt)^2)^{1/2}}$

It is interesting to note that we can write V & \vec{A} in terms of the instantaneous position of the charge!



then $R^2 = x^2 + (z-vt)^2$

$x^2(1-v^2/c^2) + (z-vt)^2 = R^2 - v^2/c^2 x^2$ w/ $x = R \sin\theta$

$= R^2(1-v^2/c^2 \sin^2\theta)$

so $V(\vec{r}, t) = \frac{q}{4\pi\epsilon_0 R} \frac{1}{\sqrt{1-v^2/c^2 \sin^2\theta}}$

$\vec{A} = \frac{\mu_0 q}{4\pi R} \frac{\vec{v}}{\sqrt{1-v^2/c^2 \sin^2\theta}}$

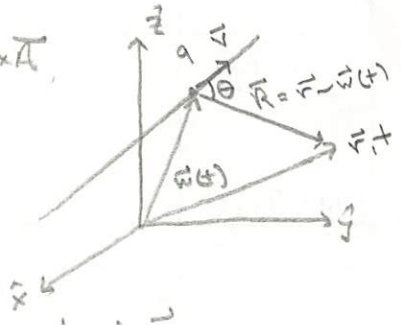
Now it's not too bad to calculate:

$\vec{E} = -\nabla V - \frac{\partial \vec{A}}{\partial t}, \vec{B} = \nabla \times \vec{A}$

you get:

$\vec{E} = \frac{q \hat{R}}{4\pi\epsilon_0 R^2} \frac{(1-v^2/c^2)}{(1-v^2/c^2 \sin^2\theta)^{3/2}}$

$\vec{B} = \frac{\mu_0 q (\vec{v} \times \hat{R}) (1-v^2/c^2)}{4\pi R^2 (1-v^2/c^2 \sin^2\theta)^{3/2}} = \frac{1}{c^2} \vec{v} \times \vec{E}$

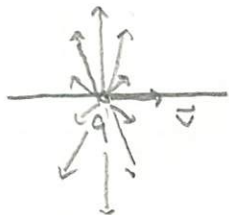


as the fields for a particle moving w/ constant velocity \vec{v} (Heaviside fields)

remember that $\vec{R} = \vec{r} - \vec{w}(t)$ here, so it's the vector pointing from the current (!) particle location to the field point.

For $v/c \ll 1, \vec{E} = \frac{q}{4\pi\epsilon_0 R^2} \hat{R} \quad \vec{B} = \frac{\mu_0 q \vec{v} \times \hat{R}}{4\pi R^2}$

What do these fields look like? At what θ is \vec{E}, \vec{B} the largest?



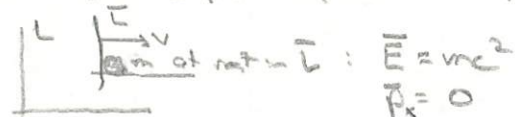
$1 - \frac{v^2}{c^2} \sin^2 \theta$ smallest for $\theta = \pi/2$

But if E is to have finite value for $m \rightarrow 0$:

$$E = \frac{mc^2}{\sqrt{1-v^2/c^2}} \quad \text{as } m \rightarrow 0, \text{ we must have } v \rightarrow c$$

"massless particles travel at c "

Aside: For the energy-momentum 4-vec: $p^\mu = (\frac{E}{c}, \vec{p})$ in the rest frame of a particle, we have:



in L: $E = \frac{mc^2}{\sqrt{1-v^2/c^2}}, \quad p_x = \frac{mv}{\sqrt{1-v^2/c^2}}$

just as $-c^2 t^2 + \vec{x}^2 = -c^2 t'^2 + \vec{x}'^2$, we have
 $-\vec{E}^2/c^2 + \vec{p}^2 = -E^2/c^2 + p_x^2$

in the rest frame, $-\vec{E}^2/c^2 + \vec{p}^2 = -m^2 c^2$

we expect: $-\vec{E}^2/c^2 + p_x^2 = -m^2 c^2$, too, of course
 let's check:

$$-\frac{m^2 c^2}{(1-v^2/c^2)} + \frac{m^2 v^2}{(1-v^2/c^2)} = \frac{-m^2 c^2 (1-v^2/c^2)}{(1-v^2/c^2)} = -m^2 c^2$$

in general: $-\vec{E}^2/c^2 + \vec{p} \cdot \vec{p} = -m^2 c^2$

for massless particles, then,

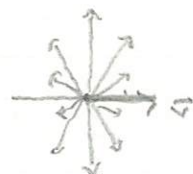
$$E^2 = \vec{p} \cdot \vec{p} c^2 \neq 0$$

Let's go back to our picture for \vec{E} generated by a charge moving w/ constant velocity:

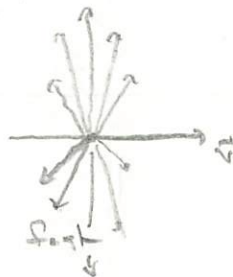
as $v \rightarrow c$, the fields "flatten"



slow



medium

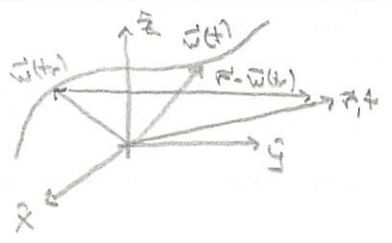


fast



this would be the electric field of a massless, charged particle.

E + B For a Point Particle



we had the LW potentials:

$$r = |\vec{r} - \vec{w}(t_r)| \quad w/$$

$$c(t - t_r) = |\vec{r} - \vec{w}(t_r)|$$

↳ $\vec{v} \equiv \dot{\vec{w}}(t_r)$, then $V(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{1}{r - \vec{r} \cdot \vec{v}/c}$

$$\vec{A}(\vec{r}, t) = \frac{\mu_0 q}{4\pi} \frac{\vec{v}}{r - \vec{r} \cdot \vec{v}/c}$$

and now it's time to compute the fields:

$$\vec{E} = -\nabla V - \frac{\partial \vec{A}}{\partial t} \quad \vec{B} = \nabla \times \vec{A}$$

The difficulty is in evaluating the derivatives of t_r .

example: $c(t - t_r) = |\vec{r} - \vec{w}(t_r)|$ take $\frac{\partial}{\partial t}$ of both sides

$$c(1 - \frac{\partial t_r}{\partial t}) = -\frac{(\vec{r} - \vec{w}(t_r)) \cdot \frac{d\vec{w}}{dt} \cdot \frac{\partial t_r}{\partial t}}{|\vec{r} - \vec{w}(t_r)|}$$

↳ use the notation defined above:

$$c(1 - \frac{\partial t_r}{\partial t}) = -\vec{r} \cdot \vec{v} \frac{\partial t_r}{\partial t}$$

$$\frac{\partial t_r}{\partial t} (1 - \frac{\vec{r} \cdot \vec{v}}{c}) = 1 \Rightarrow \frac{\partial t_r}{\partial t} = \frac{1}{1 - \vec{r} \cdot \vec{v}/c}$$

and sim. $\nabla t_r = -\frac{\hat{r}/c}{1 - \vec{r} \cdot \vec{v}/c}$

Putting all the pieces together, we have, letting

$$u \equiv c\hat{r} - \vec{v} \quad \vec{a} \equiv \ddot{\vec{w}}(t_r)$$

$$\vec{E}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{c}{(u \cdot \vec{r})^3} \left[(c^2 - v^2)\vec{u} + \vec{r} \times (\vec{u} \times \vec{a}) \right]$$

$$\vec{B} = \frac{1}{c} \hat{r} \times \vec{E}$$