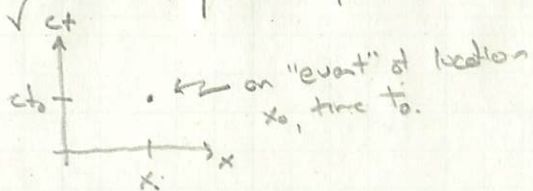
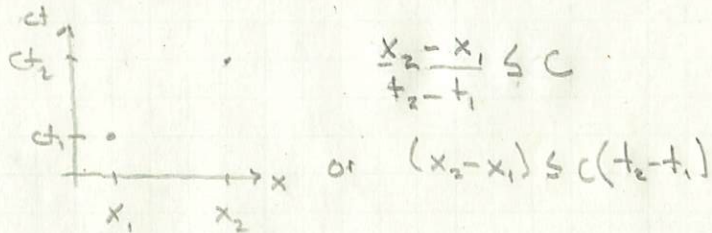


## Minkowski Diagrams & Causality

A Minkowski diagram is a plot of points in the  $x$ - $ct$  plane.



An event at  $x_1, t_1$  can cause an event at  $x_2, t_2$  if a signal can travel from  $x_1$  to  $x_2$  at a speed  $\leq c$ .

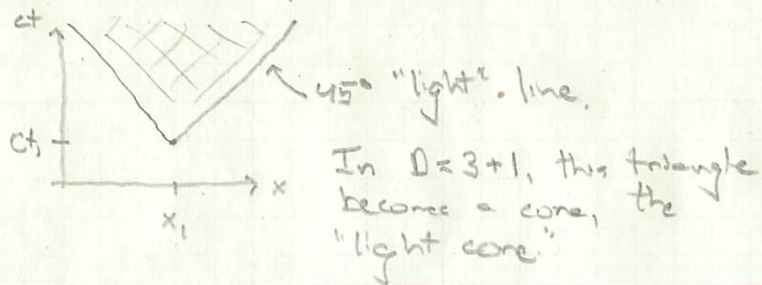


the requirement, written in terms of the Minkowski distance (squared) is

$$-c^2(t_2 - t_1)^2 + (x_2 - x_1)^2 \leq 0$$

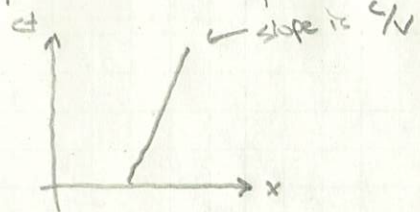
(such an interval is called "time-like")

Given a point  $x_1, t_1$ , the region of "causal influence" is the set of all points in causal contact w/  $x_1, t_1$ :



## Motion

For a particle traveling at speed  $v$ :  $x = vt$ , or  $ct = \frac{c}{v} x$



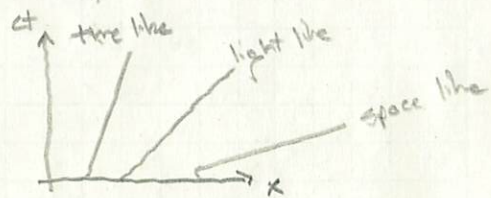
lines w/ slope  $> 1$  have

$$c/v > 1 \Rightarrow v < c$$

particle motion occurs w/  $v < c$ .

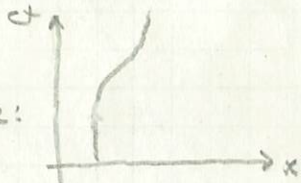
For light:  $x = ct \Rightarrow ct = x$ , the slope is 1

Slopes  $< 1$  have  $v > c$



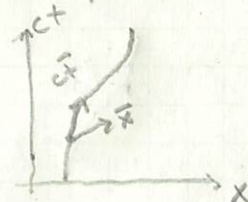
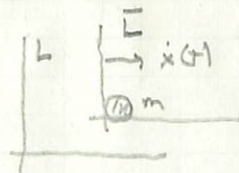
for non-constant vel. motion:

? tell the "story" of motion here:



## Proper Time

Given a curve  $x(t)$ , at any  $t$ , we can make a Lorentz boost into the "rest-frame" of a particle moving according to  $x(t)$ :



In L:  $ds^2 = -c^2 dt^2 + dx^2$ , for a small interval

In  $\bar{L}$ :  $d\bar{s}^2 = -c^2 d\bar{t}^2 + d\bar{x}^2$  rest frame has  $d\bar{x} = 0$ .

But  $d\bar{s}^2 = ds^2 \Rightarrow -c^2 d\bar{t}^2 = -c^2 dt^2 + dx^2$   
 $= -c^2 dt^2 + v^2 dt^2$

the relation between  $t$  &  $\bar{t}$  is given by

$$d\bar{t}^2 = dt^2 (1 - v^2/c^2) \Rightarrow \frac{dt}{d\bar{t}} = \frac{1}{\sqrt{1 - v^2/c^2}}$$

In this context  $d\bar{t}$  is a "proper time" interval, w/  $\bar{t}$  defined in the instantaneous rest frame of the particle - often denoted  $\tau$ :

$$\frac{dt}{d\tau} = \frac{1}{\sqrt{1 - v^2/c^2}} = \frac{1}{\sqrt{1 - \beta^2}}$$

$\beta = v/c$   
 $v = \dot{x} = \dot{y} = \dot{z}$

### Lorentz Vectors

For a Lorentz boost in the x-direction:

$$\begin{pmatrix} c d\bar{t} \\ d\bar{x} \\ d\bar{y} \\ d\bar{z} \end{pmatrix} = \begin{pmatrix} \gamma & -\gamma v/c & 0 & 0 \\ -\gamma v/c & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} c dt \\ dx \\ dy \\ dz \end{pmatrix} \quad (*)$$

$$d\bar{x}^\mu = \sum_{\nu=0}^3 \Lambda^\mu_{\nu} dx^\nu \quad \text{for } \mu=0,1,2,3 \quad (+)$$

$\uparrow$   
time      space

we call  $dx^\mu$  a "4-vector" - anything else w/ 4-components, (all w/ the same units) that responds to a Lorentz transformation like (\*) is also called a 4-vector.

Example  $\eta^\mu \equiv \frac{dx^\mu}{d\tau}$  is a 4-vector

to see this, take carry out a Lorentz transformation:

$$\eta^\mu = \frac{d\bar{x}^\mu}{d\bar{\tau}} \quad \text{note that } d\bar{\tau} = d\tau, \text{ the proper time elapsed is unchanged by the boost.}$$

$$= \frac{d\bar{x}^\mu}{d\tau} = \sum_{\nu=0}^3 \Lambda^\mu_{\nu} \frac{dx^\nu}{d\tau} = \sum_{\nu=0}^3 \Lambda^\mu_{\nu} \eta^\nu \quad \text{for } \mu=0,1,2,3$$

matching (+) (which is equivalent to (1))

$\eta^\mu \equiv \frac{dx^\mu}{d\tau}$  is the "4-velocity"

w/ components:  $\eta^0 = c \frac{dt}{d\tau}$ ,  $\eta^i = \frac{dx^i}{d\tau}$   $i=1,2,3$

How is  $\eta^\mu$  related to  $\frac{dx^i}{dt} \equiv v^i$  ( $i=1,2,3$ )?

$$\eta^\mu = \frac{dx^\mu}{d\tau} = \frac{dx^\mu}{dt} \frac{dt}{d\tau} = \frac{1}{\sqrt{1 - v^2/c^2}} \begin{pmatrix} c \\ v_x \\ v_y \\ v_z \end{pmatrix}$$

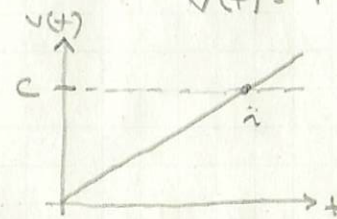
When... "updating" non-relativistic expressions to take SR into account, we have to decide whether to use  $t$  or  $\tau$  - they are the same for  $v \ll c$ .

## Newton's 2nd Law

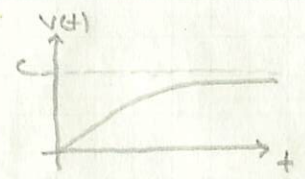
Working in one-dimension, Newton's 2nd law is:

$$\frac{dp}{dt} = F \quad \text{w/ } p = mv \quad (*)$$

issue: for  $F = F_0$ , constant,  $p(t) = F_0 t$   
then  $v(t) = p(t)/m = F_0/m t$



now:



starts off w/  $v \approx F_0/m t$  (linear), but asymptotically approaches  $c$ .

$p^\mu \equiv m \frac{dx^\mu}{dr}$  is the "relativistic 4-momentum" it is a 4-vector.

the spatial components are  $\vec{p} = m\vec{v} = \frac{m\vec{v}}{\sqrt{1-v^2/c^2}}$

How about  $p^0$ ?  $p^0 = mc \frac{dt}{dr} = \frac{mc}{\sqrt{1-v^2/c^2}} = \frac{1}{c} \left[ \frac{mc^2}{\sqrt{1-v^2/c^2}} \right]$   
                   $\downarrow$   
                   $= E/c$

How should we update (\*) to bring the predicted motion in line w/ SR?

$$\frac{dp}{dt} = F \quad \text{w/ } p = m\vec{v} = \frac{m\vec{v}}{\sqrt{1-v^2/c^2}}$$

we still have  $p(t) = F_0 t$  for constant force, but:

$$p = \frac{mv}{\sqrt{1-v^2/c^2}} \Rightarrow p^2(1-v^2/c^2) = m^2 v^2$$
$$p^2 = v^2(m^2 + p^2/c^2)$$

$$\text{so } v = \frac{p/m}{\sqrt{1 + (p/mc)^2}} \xrightarrow{p \rightarrow \infty} c \quad \checkmark$$

all 4 components of  $p^\mu$  have units of momentum.

? Any other sets of 4 things w/ the same units (allowing only  $c$  to convert, as in  $p^\mu$ )?

? Why isn't Newton's 2nd law:  $\frac{dp}{dt} = F$  in SR?