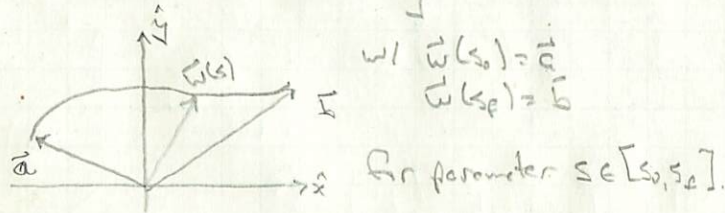
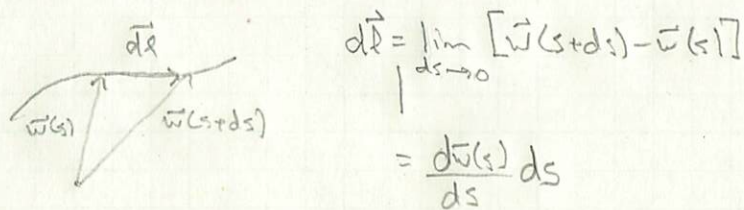


# Line Integrals

A curve can be described by a vector  $\vec{w}(s)$ :



The tangent to the curve,  $d\vec{l}$ , is related to the derivative of  $\vec{w}(s)$ :

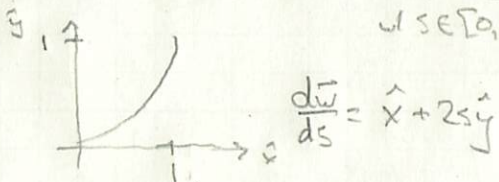


A typical type of integral along a curve has the form:

$$I = \int_a^b \vec{v} \cdot d\vec{l} = \int_{s_0}^{s_1} \vec{v} \cdot \frac{d\vec{w}}{ds} ds$$

for a vector function  $\vec{v}$  (think of work)

example: For the curve  $\vec{w}(s) = s\hat{x} + s^2\hat{y}$  w/  $s \in [0, 1]$



along the curve, we have:  $x = s, y = s^2$

take  $\vec{v} = \alpha x\hat{x} + \beta xy\hat{y}$  as our vector function, evaluated along the curve,

$$\vec{v}|_w = \frac{\alpha s}{x} \hat{x} + \frac{\beta s}{x} \frac{s^2}{y} \hat{y}$$

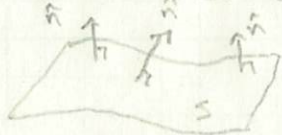
$$\vec{v}|_w \cdot d\vec{l} = (\alpha s \hat{x} + \beta s^3 \hat{y}) \cdot (\hat{x} + 2s \hat{y}) ds$$

$$= (\alpha s + 2\beta s^4) ds$$

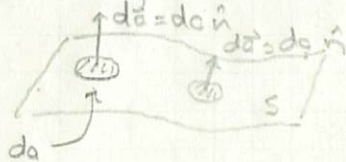
$$I = \int_{\vec{a}=0}^{\vec{b}=\hat{x}+\hat{y}} \vec{v} \cdot d\vec{l} = \int_0^1 (\alpha s + 2\beta s^4) ds = \frac{1}{2}\alpha + \frac{2}{5}\beta$$

# Surface Integrals

A surface has a unit normal (that can vary over the surface)



define  $d\vec{a}$  to be a vector w/ magnitude that is an infinitesimal area,  $\hat{n}$  as its direction



Given a vector function  $\vec{v}$ , we are interested in

$$I = \int_S \vec{v} \cdot d\vec{a} \quad (\text{Flux, for instance, hence the dot product})$$

## Volume Integrals

Given a volume  $\Omega$   
we have infinitesimal  
volume elt  $dV$



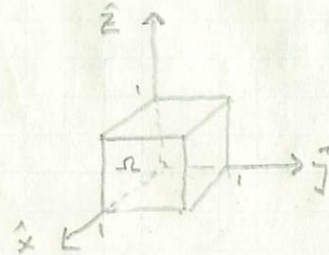
w/

$$dV = dx dy dz \quad (\text{in Cartesian coordinates})$$

here, the main integral of interest is:

$$I = \int_{\Omega} f dV \quad \text{for a function } f(x, y, z)$$

example:



take

$$f = \alpha x^2 y z$$

$$\int_{\Omega} f dV = \int_0^1 \int_0^1 \int_0^1 \alpha x^2 y z dx dy dz$$

$$= \int_0^1 \int_0^1 \frac{1}{3} \alpha y z dy dz = \int_0^1 \frac{1}{6} \alpha z dz = \frac{1}{12} \alpha$$

## Fundamental Theorem(s) of Calculus

In one dimension:  $I = \int_a^b \frac{df(x)}{dx} dx = f(b) - f(a)$

the integral of the derivative of  $f(x)$  for  $x \in [a, b]$   
is equal to  $f$  evaluated on the boundaries  
of the domain.

example:

(surface has  $z=0$ )  
 $d\vec{a} = dx dy \hat{k}$

take  $\vec{v} = \alpha xy \hat{k}$ , then

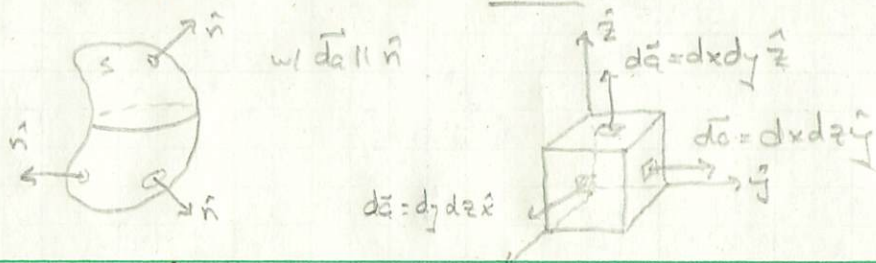
$$\int_S \vec{v} \cdot d\vec{a} = \int_0^1 \int_0^1 (\alpha xy \hat{k}) \cdot (dx dy \hat{k})$$

$$= \int_0^1 \int_0^1 \alpha xy dx dy = \int_0^1 \frac{1}{2} \alpha y dy = \frac{1}{4} \alpha$$

"open surfaces" have  $\hat{n}$  that can be "above" or "below"



"closed surfaces," for which there is an inside to an outside have unit outward normal



integration over a closed surface:  $\oint \vec{v} \cdot d\vec{a}$



there are different flavors for line, surface, & volume integrals.

1. line integrals:  $I = \int_a^b \vec{v} \cdot d\vec{l}$

we want  $\vec{v}$  to "be a derivative" but of what?

one option:  $\vec{v} = \nabla f$

(aside - notation  $f(x, y, z) \rightarrow f(\vec{r})$  w/  $\vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$ )

for a curve specified by  $\vec{w}(s)$ , w/  $d\vec{l} = \frac{d\vec{w}(s)}{ds} ds$ , we have

$$\int_a^b \nabla f \cdot d\vec{l} = \int_{s_0}^{s_1} \nabla f \cdot d\vec{l} = \int_{s_0}^{s_1} \frac{df(\vec{w}(s))}{ds} ds = f(\vec{w}(s_1)) - f(\vec{w}(s_0)) = f(\vec{b}) - f(\vec{a})$$

Level along the curve

The result,  $\int_a^b \nabla f \cdot d\vec{l} = f(\vec{b}) - f(\vec{a})$  (\*)

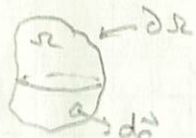
is familiar from conservative forces ( $\vec{F} = -\nabla U$ ) when calculating work.

Note that  $\oint \nabla f \cdot d\vec{l} = 0$  follows from (\*)

2. Volume integrals:

$$\int_{\Omega} (\nabla \cdot \vec{v}) d\tau = \oint_{\partial\Omega} \vec{v} \cdot d\vec{a}$$

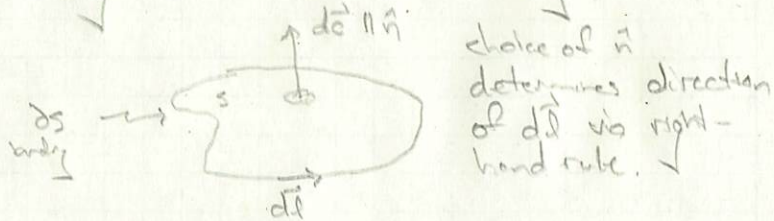
derivative of  $\vec{v}$  evaluated "in the bulk"       $\vec{v}$  evaluated on surface



the "?" must be a scalar - most natural is  $\vec{v} \cdot d\vec{a}$  (gets the  $D=1$  limit right)

$$\int_{\Omega} (\nabla \cdot \vec{v}) d\tau = \oint_{\partial\Omega} \vec{v} \cdot d\vec{a} \quad (\text{divergence theorem})$$

3. Surface integrals: for open  $\Sigma$  w/ boundary  $\partial\Sigma$



$$\int_{\Sigma} (\nabla \times \vec{v}) \cdot d\vec{a} = \int_{\partial\Sigma} (\text{scalar} \sim \vec{v}, \text{ must involve } d\vec{l}) \dots$$