

Last time $f: M \rightarrow \mathbb{R} \implies df_p: T_p M \rightarrow \mathbb{R}$, i.e. $df \in T_p^* M$.

In local coords.,

$$(*) \quad df_p = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(p) dx_{i,p}.$$

really $\frac{\partial(f \circ h^{-1})}{\partial x_i}(p)$

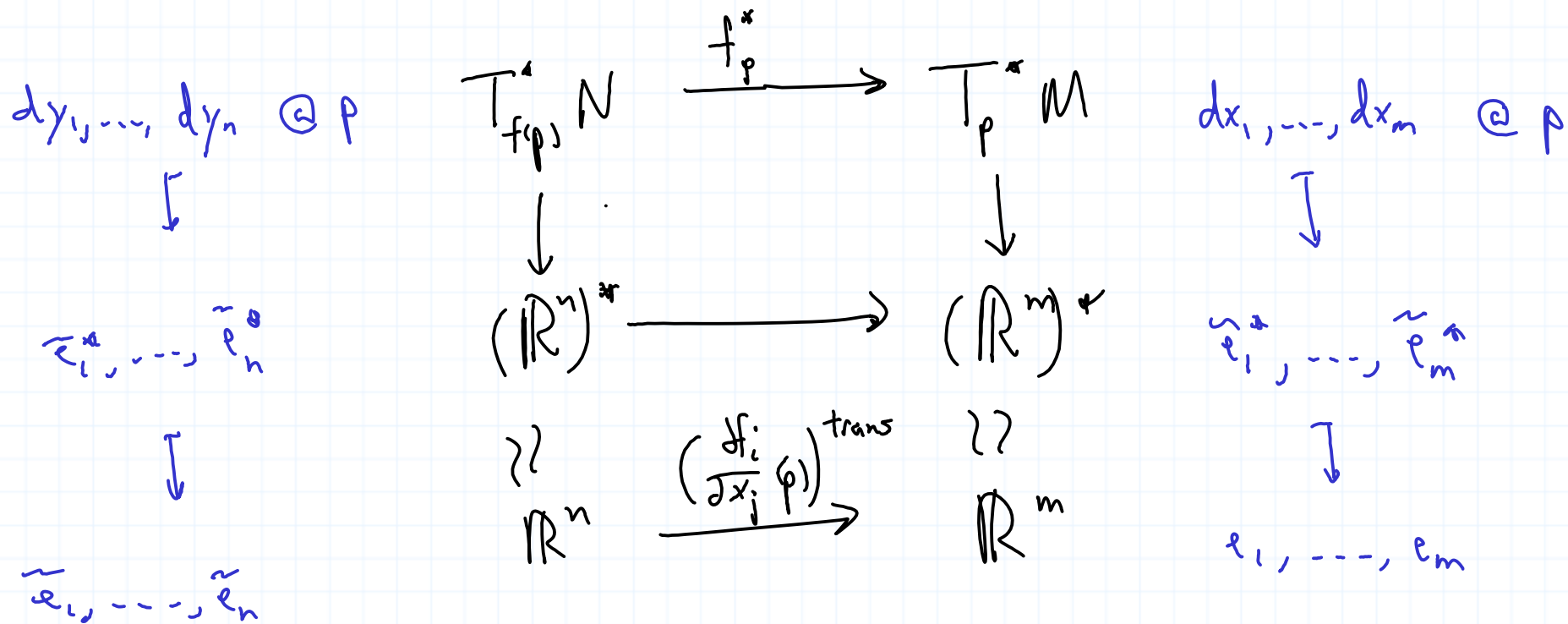
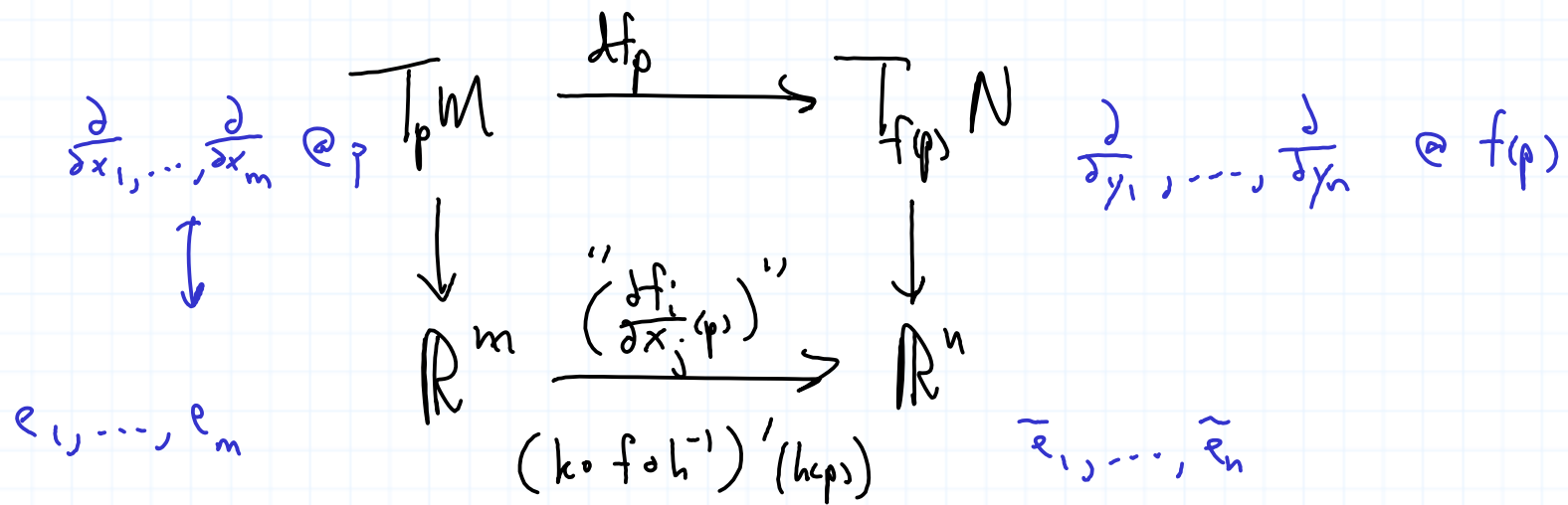
For general $f: M \rightarrow N$ we get $f_{*,p} := df_p: T_p M \rightarrow T_{f(p)} N$

and, thus, $f_p^* := df_p^*: T_{f(p)}^* N \rightarrow T_p^* M$ and

$f_p^*: \Lambda^k T_{f(p)}^* N \rightarrow \Lambda^k T_p^* M$. In coords. (U, h) at p , (V, k) at

$f(p)$ with $U \subseteq f^{-1}(V)$:

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Thus, $df_p^*(dy_i) =$ i th column of $(\frac{df_i}{dx_j}(p))^{\text{trans}}$
 $=$ i th row of $(\frac{df_i}{dx_j}(p)) = \nabla f_i(p)$
 $=$ $\sum_j \frac{df_i}{dx_j}(p) dx_j = df_{i,p}$

$df_p^*(dy_i) = df_{i,p}$

Thus, $f_p^*: \Lambda_{f(p)}^k T^*N \longrightarrow \Lambda^k T_p^*M$ is given locally by

$f_p^*(\sum_m w_m(f(p)) dx_{m_1} \wedge \dots \wedge dx_{m_k}) = \sum_m w_m(f(p)) df_{m_1} \wedge \dots \wedge df_{m_k}.$

Bundles

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$f: M \rightarrow N$ induces mappings of bundles

$$f_*: TM \rightarrow TN$$

$$f^*: \Omega^k N \rightarrow \Omega^k M.$$

For instance, in local coords (U, h) , (V, k) , as usual,

$$\begin{array}{ccc} \pi_M^{-1}(U) & \xrightarrow{f_*} & \pi_N^{-1}(V) \\ \Downarrow & & \Downarrow \\ h(U) \times \mathbb{R}^m & \longrightarrow & k(V) \times \mathbb{R}^n \\ (h(p), v) & \longmapsto & (k(f(p)), f_{*,p}(v)) \end{array}$$

Point: The mappings we defined locally (at each point p , above) glue together to give (smooth) mappings of bundles.

Example $M = \mathbb{R}^2$, $N = \mathbb{R}^3$

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$$f: \mathbb{R}^2 \longrightarrow \mathbb{R}^3 \\ (u, v) \longmapsto (u^2 - v, u + 2v, v^2)$$

$$w = \underbrace{x^2}_{w_{xy}(x,y,z)} dx \wedge dy + \underbrace{(x+z)}_{w_{yz}(x,y,z)} dy \wedge dz \\ \in \int^2 \mathbb{R}^3 = \text{sections of } \Lambda^2 T^* \mathbb{R}^3$$

$$f^*(w) = \underbrace{u^2 - v}_{w_{xy}(f(u,v))} d(u^2 - v) \wedge d(u + 2v) + \underbrace{(u^2 - v + v^2)}_{w_{yz}(f(u,v))} d(u + 2v) \wedge dv^2 \\ = (u^2 - v) (2u du - dv) \wedge (du + 2dv) + (u^2 - v + v^2) (du + 2dv) \wedge (2v dv) \\ \uparrow \\ \text{by } (*), \text{ page 1} \\ = [(u^2 - v)(4u + 1) + 2(u^2 - v + v^2)v] du \wedge dv = (\text{etc}) du \wedge dv.$$

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Orientation

Def. Let V be a real vector space. Two ordered bases (v_1, \dots, v_n) and (w_1, \dots, w_n) have the **same orientation** if the

mapping

$$\begin{array}{ccc} V & \longrightarrow & V \\ v_i & \longmapsto & w_i \end{array}$$

has positive determinant.

The property of having the same orientation defines an equivalence relation on the set of ordered bases for V with two equivalence classes. Each equivalence class is called an **orientation** on V .

Having chosen an orientation \mathcal{O} , we get an **oriented vector space**, (V, \mathcal{O}) .

If an ordered basis (w_1, \dots, w_n) is in \mathcal{O} , we say (w_1, \dots, w_n) is positively oriented; otherwise it's negatively oriented.

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Example. $V = \mathbb{R}^3$

$$(e_1, e_2, e_3) \sim (e_2, e_3, e_1) \sim (e_3, e_1, e_2)$$
$$(e_2, e_1, e_3) \sim (e_1, e_3, e_2) \sim (e_3, e_2, e_1)$$

Also, for example, $(e_1 + e_2, e_2, e_3) \sim (e_1, e_2, e_3)$ since

$\mathbb{R}^3 \xrightarrow{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}} \mathbb{R}^3$ has positive determinant.

e_1	\mapsto	$e_1 + e_2$
e_2	\mapsto	e_2
e_3	\mapsto	e_3