

Last time

$$Q: D \rightarrow \mathbb{R}^n \quad w/ D \subseteq \mathbb{R}^k,$$

$$w = \sum_{\mathcal{I}} f_{\mathcal{I}} dx_{\mathcal{I}} \in \Omega^k \mathbb{R}^n \quad f_{\mathcal{I}} = f_{\mathcal{I}}(x_1, \dots, x_n)$$

$\mathcal{I} = (i_1, \dots, i_k)$

Q^*w is formed from w by substituting $x_i = Q_i$. i -th component of Q

Prop. $Q^*w = \sum_{\mathcal{I}} f_{\mathcal{I}} \circ Q \det(JQ_{\mathcal{I}}) du_{\mathcal{I}}$

where $JQ_{\mathcal{I}}$ is the $k \times k$ submatrix formed by all columns of Q and the rows determined by \mathcal{I} ; and $du_{\mathcal{I}} = du_{i_1} \wedge \dots \wedge du_{i_k}$.

Pf/ It suffices to consider the case $w = dx_{i_1} \wedge \dots \wedge dx_{i_k}$.

Then $Q^*w = dQ_{i_1} \wedge \dots \wedge dQ_{i_k}$

$$= \left[\sum \frac{\partial \phi_{i_1}}{\partial u_i} du_i \right] \wedge \dots \wedge \left[\sum \frac{\partial \phi_{i_k}}{\partial u_i} du_i \right]$$

$$= \boxed{?} du_1 \wedge \dots \wedge du_k .$$

The du_i just serve as "placeholders". We might as well replace them with the standard basis vectors e_i . Our calculation then becomes

$$(\star) \left[\sum \frac{\partial \phi_{i_1}}{\partial u_i} e_i \right] \wedge \dots \wedge \left[\sum \frac{\partial \phi_{i_k}}{\partial u_i} e_i \right]$$

$$= \boxed{?} e_1 \wedge \dots \wedge e_k$$

Where $\boxed{?}$ is the same as above.

But (\star) is just $v_1 \wedge \dots \wedge v_k$ where $v_j = \left(\frac{\partial \phi_{i_1}}{\partial u_1}, \dots, \frac{\partial \phi_{i_1}}{\partial u_k} \right)_j$, and we've already seen that $v_1 \wedge \dots \wedge v_k = \det(v_1, \dots, v_k) e_1 \wedge \dots \wedge e_k$. \square

Remark The Proposition we just proved holds for pulling back

(3)

k -forms in \mathbb{R}^n along k -surfaces. What about pulling back an l -form for $l < k$? (If $l > 0$, the pullback would be 0.)

Consider the form $w = dx_{i_1} \wedge \dots \wedge dx_{i_l}$. Then

$$\mathcal{Q}^* w = \sum_C g_C du_C \quad \text{where each } C \text{ ranges over all}$$

possible (c_1, \dots, c_l) with $1 \leq c_1 < \dots < c_l \leq k$, i.e. $\mathcal{Q}^* w$.

Arguing as in the Proposition, we have g_C is the determinant of the $l \times l$ submatrix of $J\mathcal{Q}$ consisting of columns C and rows i_1, \dots, i_l .

Basic properties of the pullback and of d

Proposition

Let $\omega \in \Omega^s \mathbb{R}^n$, $\eta \in \Omega^t \mathbb{R}^n$, $\lambda \in \mathbb{R}$, $\varphi: D \xrightarrow{c, \mathbb{R}^k} \mathbb{R}^n$.

(4)

1. The pullback and d are linear (over \mathbb{R}):

$$\varphi^*(\lambda\omega + \eta) = \lambda \varphi^*\omega + \varphi^*\eta,$$

$$d(\lambda\omega + \eta) = \lambda d\omega + d\eta.$$

$$2. \quad \varphi^*(\omega \wedge \eta) = \varphi^*\omega \wedge \varphi^*\eta$$

$$d(\omega \wedge \eta) = d\omega \wedge \eta + (-1)^s \omega \wedge d\eta$$

$$3. \quad \varphi^*(d\omega) = d(\varphi^*\omega)$$

4. If $D \xrightarrow{\varphi} \mathbb{R}^n \xrightarrow{\psi} \mathbb{R}^m$ and $\alpha \in \Omega^l \mathbb{R}^m$, then

$$(\psi \circ \varphi)^*(\alpha) = \varphi^*(\psi^*\alpha).$$

$$5. \quad d^2 = 0.$$

Discussion / (1) follows directly from the definitions, as does the first part of (2). For the second part of 2, by linearity, it suffices to consider the case $\omega = f dx_I$ and $\eta = g dx_J$ for some index sets I and J :

(5)

$$\begin{aligned} d(\omega \wedge \eta) &= d((f dx_I) \wedge (g dx_J)) \\ &= d(fg dx_I \wedge dx_J) \\ &= [d(fg)] \wedge dx_I \wedge dx_J \\ &= \left[\sum_i \frac{\partial}{\partial x_i} (fg) dx_i \right] \wedge dx_I \wedge dx_J \\ &= \left[g \sum_i \frac{\partial f}{\partial x_i} dx_i + f \sum_i \frac{\partial g}{\partial x_i} dx_i \right] \wedge dx_I \wedge dx_J \end{aligned}$$

product rule

$$= \left[g \sum \frac{\partial f}{\partial x_i} dx_i \right] \wedge dx_{\mathbb{I}} \wedge dx_{\mathbb{J}} + \left[f \sum \frac{\partial g}{\partial x_i} dx_i \right] \wedge dx_{\mathbb{I}} \wedge dx_{\mathbb{J}} \quad \textcircled{6}$$

$$= \left[\sum \frac{\partial f}{\partial x_i} dx_i \right] \wedge dx_{\mathbb{I}} \wedge (g dx_{\mathbb{J}}) + f dx_{\mathbb{I}} \wedge \left[\sum \frac{\partial g}{\partial x_i} dx_i \right] \wedge dx_{\mathbb{J}}$$

$$= (df \wedge dx_i) \wedge (g dx_{\mathbb{J}}) + (-1)^s (f dx_{\mathbb{I}}) \wedge (dg \wedge dx_{\mathbb{J}})$$

$$= d\omega \wedge \eta + (-1) \omega \wedge d\eta.$$

For (3), by linearity we may assume $\omega = f dx_{\mathbb{I}}$. Then

$$\mathcal{Q}^*(d\omega) = \mathcal{Q}^*(df \wedge dx_{\mathbb{I}}) = \mathcal{Q}\left(\sum_i \frac{\partial f}{\partial x_i} dx_i \wedge dx_{\mathbb{I}}\right) = \sum_i \frac{\partial f}{\partial x_i} \circ \mathcal{Q} \, d\mathcal{Q}_i \wedge d\mathcal{Q}_{\mathbb{I}}$$

$$= \sum_i \frac{\partial f}{\partial x_i} \circ \mathcal{Q} \left(\sum_j \frac{\partial \mathcal{Q}_i}{\partial u_j} du_j \right) \wedge d\mathcal{Q}_{\mathbb{I}} = \sum_{i,j} \frac{\partial f}{\partial x_i} \circ \mathcal{Q} \frac{\partial \mathcal{Q}_i}{\partial u_j} du_j \wedge d\mathcal{Q}_{\mathbb{I}}$$

chain rule

$$= \sum \frac{\partial f \circ \mathcal{Q}}{\partial u_j} du_j \wedge d\mathcal{Q}_{\mathbb{I}} = d(f \circ \mathcal{Q}) \wedge d\mathcal{Q}_{\mathbb{I}} = d(\mathcal{Q}^*(f \wedge dx_{\mathbb{I}})) = d(\mathcal{Q}^*\omega).$$

(4) is straightforward: substitute, then substitute again. \square

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(5): Again by linearity, we may assume $w = f dx_I$.

$$\text{Then } d^2 w = d(dw) = d(df \wedge dx_I) = d\left[\left(\sum_i \frac{\partial f}{\partial x_i} dx_i\right) \wedge dx_I\right]$$

$$= \sum_i d\left(\frac{\partial f}{\partial x_i} dx_i \wedge dx_I\right) = \sum_i d\left(\frac{\partial f}{\partial x_i}\right) \wedge dx_i \wedge dx_I$$

$$= \sum_i \left(\sum_j \frac{\partial^2 f}{\partial x_j \partial x_i} dx_j\right) \wedge dx_i \wedge dx_I$$

$$= \sum_{i < j} \frac{\partial^2 f}{\partial x_j \partial x_i} dx_j \wedge dx_i \wedge dx_I$$

For each pair of indices $1 \leq a \leq b \leq n$. There is a term in the sum corresponding to $i=a$ and $j=b$:

$$\frac{\partial^2 f}{\partial x_b \partial x_a} dx_b \wedge dx_a \wedge dx_I$$

and a term corresponding to $i=b$ and $j=a$:

$$\frac{\partial^2 f}{\partial x_a \partial x_b} dx_a \wedge dx_b \wedge dx_I.$$

⑧

If $a=b$, the term is 0. Otherwise these two terms cancel out since $dx_b \wedge dx_a = -dx_a \wedge dx_b$.

We are assuming that f is nice enough so that

$$\frac{\partial^2 f}{\partial x_b \partial x_a} = \frac{\partial^2 f}{\partial x_a \partial x_b}, \text{ by the way. } \square$$

Bonus result: If $\omega \in \Omega^s \mathbb{R}^n$ and $\eta \in \Omega^t \mathbb{R}^n$, then

$$\omega \wedge \eta = (-1)^{st} \eta \wedge \omega.$$