

Special Cases:

1) weighted length of a curve in \mathbb{R}^n

$$C: [a, b] \rightarrow \mathbb{R}^n, \quad f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$\text{length}_f(C) = \text{area}(C) = \int_C f := \int_D f \circ C |C'|.$$

2) weighted area of a surface in \mathbb{R}^3

$$D \subseteq \mathbb{R}^2, \quad S: D \rightarrow \mathbb{R}^3, \quad f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$S_u = \frac{\partial S}{\partial u}, \quad S_v = \frac{\partial S}{\partial v}.$$

$$\text{area}_f(S) = \int_S f := \int_D f \circ S |S_u \times S_v|.$$

3) weighted n -dimensional volume of an n -surface

$$D \subseteq \mathbb{R}^n, \quad V: D \rightarrow \mathbb{R}^n,$$

$$\text{area}_f(V) = \text{vol}_f(V) = \int_V f := \int_D f \circ V |\det J_V|$$

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If V is 1-1 except on a set of volume zero, then

$$\int_V f = \int_{V(D)} f.$$

↖ weighted n-dimensional volume of the set $V(D) \subseteq \mathbb{R}^n$

This comes from the change of variables theorem:



$$\int_{V(D)} f = \int_D f \circ V |\det JV|.$$

Stokes' theorem, vector fields, gradient, curl, divergence

$$w \in \Omega^k \mathbb{R}^n \quad \text{k-form in } \mathbb{R}^n$$

$$D \subseteq \mathbb{R}^k, \quad S: D \rightarrow \mathbb{R}^n \quad \text{k-surface in } \mathbb{R}^n$$

$$\int_S \omega := \int_D S^* \omega$$

← Substitute the i^{th} component of S , $S_i(u_1, \dots, u_k)$ for the i^{th} variable, x_i .

Write $S^* \omega = g \, du_1 \wedge \dots \wedge du_k$ for some g . Then $\int_D S^* \omega := \int_D g =$ weighted k -dimensional volume of D .

Stokes' If $\omega \in \Omega^{k-1} \mathbb{R}^n$, a $(k-1)$ -form, and $S: D \rightarrow \mathbb{R}^n$ is a k -surface, then

$$\int_{\partial S} \omega = \int_S d\omega,$$

where ∂S is the boundary of S .

Flow of a vector field along a curve (work if F is thought of as a force) ⑤

$C: [a, b] \rightarrow \mathbb{R}^n$ curve in \mathbb{R}^n
 $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$ vector field in \mathbb{R}^n

$\omega_F = F_1 dx_1 + \dots + F_n dx_n$ flow form

component of F along C
 \downarrow
 $= \int_a^b \left[(F \circ C) \cdot \frac{C'}{|C'|} \right] |C'| = \text{weighted length of } C$
 \downarrow dot product

flow of F along $C = \int_C F \cdot \vec{t} := \int_C \omega_F = \int_a^b (F \circ C) \cdot C'$

Flux of a vector field through a hypersurface

$D \subseteq \mathbb{R}^{n-1}$, $S: D \rightarrow \mathbb{R}^n$ hypersurface in \mathbb{R}^n
 $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$ vector field in \mathbb{R}^n

$\omega^F = \sum_{i=1}^n (-1)^{i+1} F_i dx_1 \wedge \dots \wedge \overline{dx_i} \wedge \dots \wedge dx_n$

flux of F through $S = \int_S F \cdot \vec{n} := \int_S \omega^F = \int_D (F \circ C) \cdot (S_{u_1} \times \dots \times S_{u_{n-1}})$

⑥

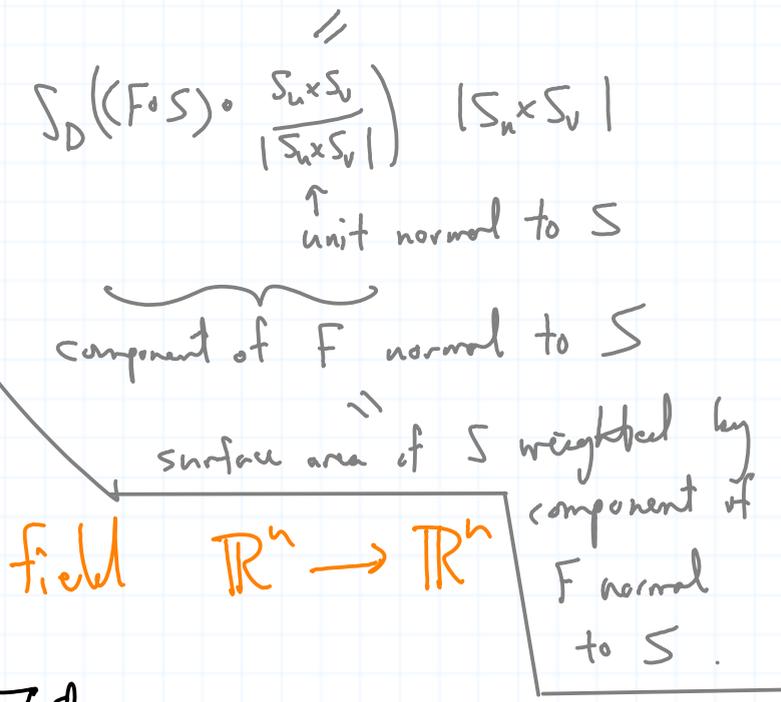
where $S_{u_1} \times \dots \times S_{u_n} = \det \begin{bmatrix} e_1 & e_2 & \dots & e_n \\ S_{u_1} & S_{u_2} & \dots & S_{u_n} \\ \vdots & \vdots & \ddots & \vdots \\ S_{u_{n-1}} & S_{u_{n-1}} & \dots & S_{u_{n-1}} \end{bmatrix}$

Classical case: $n=3$

$$\omega^F = F_1 dx \wedge dz - F_2 dx \wedge dy + F_3 dy \wedge dz$$

$$S_u \times S_v = \det \begin{bmatrix} i & j & k \\ S_{u1} & S_{u2} & S_{u3} \\ S_{v1} & S_{v2} & S_{v3} \end{bmatrix}$$

$$\int_S F \cdot \vec{n} = \int_D (F \circ S) \cdot (S_u \times S_v)$$



Classical Cases of Stokes' Theorem

$n=0,1$

$Q: \mathbb{R}^n \rightarrow \mathbb{R}$ 0-form, potential function

$\nabla Q = \text{grad } Q = \left(\frac{\partial Q}{\partial x_1}, \dots, \frac{\partial Q}{\partial x_n} \right)$ gradient vector field $\mathbb{R}^n \rightarrow \mathbb{R}^n$

$dQ = \sum \frac{\partial Q}{\partial x_i} dx_i = \omega_{\nabla Q} = \text{flow form for } \nabla Q$

Stokes: $C: [a, b] \rightarrow \mathbb{R}^n$ curve in \mathbb{R}^n

$$\int_C \nabla \phi \cdot \vec{t} = \int_C d\phi = \int_{\partial C} \phi = \phi(C(b)) - \phi(C(a))$$

The flow of a gradient vector field along a curve C is equal to the change in potential.

$$\nabla = (D_1, D_2, D_3)$$
$$D_1 = \frac{\partial}{\partial x}, D_2 = \frac{\partial}{\partial y}, D_3 = \frac{\partial}{\partial z}$$

$n = 1, 2$

$$F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

$$\nabla \times F = \text{curl } F = \det \begin{bmatrix} i & j & k \\ D_1 & D_2 & D_3 \\ F_1 & F_2 & F_3 \end{bmatrix} = (D_2 F_3 - D_3 F_2, D_3 F_1 - D_1 F_3, D_1 F_2 - D_2 F_1)$$

flow form for F

$$d\omega_F = \omega^{\nabla \times F}$$

flux form for $\nabla \times F$

Stokes' $D \subseteq \mathbb{R}^2, S: D \rightarrow \mathbb{R}^3$ surface in \mathbb{R}^3

$$\int_S (\nabla \times F) \cdot \vec{n} = \int_S \omega^{\nabla \times F} = \int_S d\omega_F = \int_{\partial S} \omega_F = \int_{\partial S} F \cdot \vec{t}$$

The flux of the curl F through S equals the circulation of F along the boundary of S .

⑧

$n = 2, 3$

$$F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

$$\nabla \cdot F = \operatorname{div} F = D_1 F_1 + D_2 F_2 + D_3 F_3$$

$$\operatorname{div} F: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$d\underbrace{w^F}_{\text{flux form for } F} = \nabla \cdot F \, dx \wedge dy \wedge dz$$

flux form for F

Stokes' $D \subseteq \mathbb{R}^3$, $V: D \rightarrow \mathbb{R}^3$ with $\det JV \geq 0$.

$$\int_V \nabla \cdot F = \int_V d w^F = \int_{\partial V} w^F = \int_{\partial V} F \cdot \vec{n}$$

The volume of V weighted by the $\operatorname{div} F$ equals the flux of F through the boundary of V .

Geometric Meaning of grad, curl, div

gradient

$v \in \mathbb{R}^3$ unit vector, $p \in \mathbb{R}^3$
rate of change

change in Q
 $=$ change density

* $(\nabla Q)(p) \cdot v =$ directional derivative of Q in the direction of v
 $= \lim_{t \rightarrow 0} \frac{Q(p+tv) - Q(p)}{t}$

* $\nabla Q(p)$ points in the direction of quickest increase of Q at p

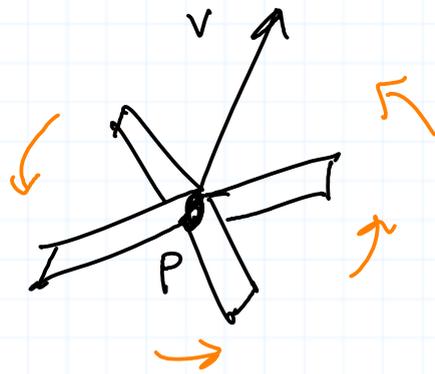
* ∇Q is perpendicular to the level set through p , $Q^{-1}(q)$

curl

$v \in \mathbb{R}^3$ unit vector, $p \in \mathbb{R}^3$

* $(\nabla \times F) \cdot v =$ circulation density of F around v in the plane perpendicular to v passing through p .

* $\nabla \times F$ points in the direction about which F spins the fastest.



divergence $p \in \mathbb{R}^3$



$D_\epsilon =$ disk of radius ϵ
perpendicular to p

$$(\nabla \times F) \cdot v = \lim_{\epsilon \rightarrow 0} \frac{1}{\text{area}(D_\epsilon)} \int_{\partial D_\epsilon} F \cdot \vec{t}$$

(10)

$\nabla \cdot F(p) =$ flux density at p .



$B_\epsilon =$ ball of radius ϵ

$$\text{div } F(p) = \lim_{\epsilon \rightarrow 0} \frac{1}{\text{vol}(B_\epsilon)} \int_{\partial B_\epsilon} F \cdot \vec{n}$$