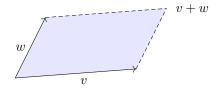
Math 201 lecture for Wednesday, Week 9

Determinants and volume

The parallelogram spanned by $v,w\in\mathbb{R}^2$ is

$$P = \{\lambda v + \mu w \colon \lambda, \mu \in [0, 1]\}$$

where $[0, 1] = \{x \in \mathbb{R} : 0 \le x \le 1\}$:



Theorem. Let A(v, w) be the area of the parallelogram spanned by $v, w \in \mathbb{R}^2$. Then

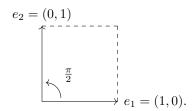
$$A(v, w) = |\det(v, w)|,$$

where det(v, w) is the determinant of the matrix with rows v and w.

Note: Since the determinant of a square matrix and its transpose are the same, A(v, w) is also the absolute value of the matrix whose *columns* are v and w.

Proof of theorem. Define SA(v, w) to be the signed area defined in the worksheet. We show that SA satisfies the properties required of a determinant function. Then, since the determinant is unique, it follows that $SA(v, w) = \det(v, w)$ and the result follows since A(v, w) = |SA(v, w)|.

• Normalized. We have $SA(e_1, e_2) = 1$:



The sign is positive since the angle from e_1 to e_2 is less than π .

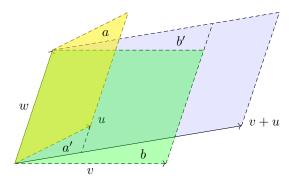
• Alternating. We have SA(v, v) = 0 since in this case, the corresponding parallelogram is degenerate.

• Multilinear.

The areas are scaled by |c| in either case since the base is scaled by |c| and the height does not change. The drawing assumes that the angle from v to w is less than π . There is a similar drawing for the case where the angle is greater than π . Either way, in the case where c < 0 note that although SA(cv, w) and SA(v, w) have opposite signs, SA(cv, w)and cSA(v, w) have the same sign.

Similar drawings show that SA(v, cw) = cSA(v, w).

$$-SA(v+u,w) = SA(v,w) + SA(u,w):$$



Note how to dissect the u-w and v-w parallelograms to get the (v + u)-w parallelogram: Cut section a in the u-w parallelogram and place it at section a', then cut section b in the v-w parallelogram and place it at section b'. The result is two parallelograms that can exactly cover the (v + u)-w parallelogram.

Of course, our drawing is just one case among the many possible angles between pairs of v, u, and w.

Definition. The parallelepided spanned by $v_1, \ldots, v_n \in \mathbb{R}^n$ is

$$P = \{\lambda_1 v_1 + \dots + \lambda_n v_n : \lambda_i \in [0, 1] \text{ for } i = 1, \dots, n\}$$



It turns out that the volume of P is given by the determinant of the matrix whose row (or columns) are v_1, \ldots, v_n :

$$\operatorname{vol}(P) = |\det(v_1, \ldots, v_n)|.$$

Note that one of the vertices of P is the origin (set $\lambda_1 = \cdots = \lambda_n = 0$). To get an arbitrary parallelepiped in \mathbb{R}^n we can just translate by any vector $u \in \mathbb{R}^n$:

$$P + u := \{p + u : p \in P\} = \{\lambda_1 v_1 + \dots + \lambda_n v_n + u : 0 \le \lambda_i \le 1 \text{ for } i = 1, \dots, n\}$$

The volume does not change:

$$\operatorname{vol}(P+u) = |\det(v_1, \dots, v_n)|.$$

Theorem. Let P be the parallelepided spanned by $v_1, \ldots, v_n \in \mathbb{R}^n$. Let $A \in M_{n \times n}(\mathbb{R})$, and let $L_A \colon \mathbb{R}^n \to \mathbb{R}^n$ be the corresponding linear function, $L_A(x) = Ax$. Then $L_A(P)$ is the parallelepiped spanned by the vectors Av_1, \ldots, Av_n , and

$$\operatorname{vol}(L_A(P)) = |\det(A)| \operatorname{vol}(P).$$

Moreover, $L_A(P+u) = L_A(P) + L_A(u)$. Thus, application of L_A scales the volumes of parallelepipeds in \mathbb{R}^n be a factor of $|\det(A)|$.

Proof. We have $x \in L_A(P)$ if and only if there exist $\lambda_1, \ldots, \lambda_n \in [0, 1]$ such that

$$x = A(\lambda_1 v_1 + \dots + \lambda_n v_n) = \lambda_1 A v_1 + \dots + \lambda_n A v_n,$$

i.e., if and only if x is in the parallelepiped determined by Av_1, \ldots, Av_n .

Let B be the matrix with columns v_1, \ldots, v_n . Then vol(P) = |det(B)|, Note that AB is the matrix whose columns are Av_1, \ldots, Av_n . It follows that

$$\operatorname{vol}(L_A(P)) = |\det(AB)| = |\det(A)| |\det(B)|.$$

We have $L_A(P+u) = L_A(P) + L_A(u)$ since L_A is linear.

Remark. To approximate the volume of an arbitrary shape in \mathbb{R}^n , one can try to dissect the shape into a union of parallelepipeds. One definition of the volume of an arbitrary shape is derived by taking limits of such approximations. One can then ask how the volume of a shape S changes under the application of a function $f: \mathbb{R}^n \to \mathbb{R}^n$. If the function is "nice" (differentiable), then at each point p in the shape, one creates a linear approximation Df(p) of the function f (called the

derivative of f at p), akin to L_A , above. Further assuming that f is injective, the volume of the image of the shape is then given by the *change of variables* formula in multivariable calculus:

$$\operatorname{vol}(f(S)) = \int_{p \in S} |\det(Df(p))|.$$

In light of the theorem we just proved, the determinant |Df(p)| should be thought of as a scaling factor. It tells us how much f scales volumes (infinitesimally) at p.