## Math 201

Section F03

September 17, 2021

## Bases

Definition. A subset $B \subset V$ is a basis if it is linearly independent and spans $V$. An ordered basis is a basis whose elements have been listed as a sequence: $B=\left\langle b_{1}, b_{2}, \ldots\right\rangle$.

## Bases

Definition. A subset $B \subset V$ is a basis if it is linearly independent and spans $V$. An ordered basis is a basis whose elements have been listed as a sequence: $B=\left\langle b_{1}, b_{2}, \ldots\right\rangle$.

## Remarks.

- Our text uses "basis" to mean "ordered basis".


## Bases

Definition. A subset $B \subset V$ is a basis if it is linearly independent and spans $V$. An ordered basis is a basis whose elements have been listed as a sequence: $B=\left\langle b_{1}, b_{2}, \ldots\right\rangle$.

## Remarks.

- Our text uses "basis" to mean "ordered basis".
- It turns out that every vector space has a basis. (Although, infinite dimensional vector spaces may not have countable bases.


## Existence of basis

Proved last time: Let $S \subseteq V$. Then $S$ is linearly dependent if and only if there exists $v \in S$ such that $v$ is a linear combination of vectors in $S \backslash\{v\}$, i.e., if and only if $v \in \operatorname{Span}(S \backslash\{v\})$.

## Existence of basis

Proved last time: Let $S \subseteq V$. Then $S$ is linearly dependent if and only if there exists $v \in S$ such that $v$ is a linear combination of vectors in $S \backslash\{v\}$, i.e., if and only if $v \in \operatorname{Span}(S \backslash\{v\})$.

It follows that
Proposition. Any finite subset $S$ of $V$ has a linearly independent subset with the same span. In other words, if $S$ is a finite set, then there is a subset of $S$ that is a basis for $\operatorname{Span}(S)$.

## Existence of basis

Proposition. If $T \subset V$ is linearly independent and $v \in V \backslash T$, then $T \cup\{v\}$ is linearly dependent if and only if $v \in \operatorname{Span}(T)$.

## Existence of basis

Proposition. If $T \subset V$ is linearly independent and $v \in V \backslash T$, then $T \cup\{v\}$ is linearly dependent if and only if $v \in \operatorname{Span}(T)$.

It again follows that
Proposition. Any finite subset $S$ of $V$ has a linearly independent subset with the same span. In other words, if $S$ is a finite set, then there is a subset of $S$ that is a basis for $\operatorname{Span}(S)$.

## Coordinates

Proposition 1. If $B$ is a basis for $V$, then every element of $V$ can be expressed uniquely as a linear combination of elements of $B$.

## Coordinates

Proposition 1. If $B$ is a basis for $V$, then every element of $V$ can be expressed uniquely as a linear combination of elements of $B$.

Proof. Since $B$ is linearly independent, we've already seen that every element in $\operatorname{Span}(B)$ can be written uniquely as a linear combination of elements of $B$.

## Coordinates

Proposition 1. If $B$ is a basis for $V$, then every element of $V$ can be expressed uniquely as a linear combination of elements of $B$.

Proof. Since $B$ is linearly independent, we've already seen that every element in $\operatorname{Span}(B)$ can be written uniquely as a linear combination of elements of $B$.

Since $B$ is a basis, $\operatorname{Span}(B)=V$.

## Example

$$
V=(\mathbb{Z} / 3 \mathbb{Z})^{3}
$$

## Example

$$
V=(\mathbb{Z} / 3 \mathbb{Z})^{3}
$$

$$
W=\left\{\left(x_{1}, x_{2}, x_{3}\right) \in V: x_{1}+x_{2}+x_{3}=0\right\}
$$

## Example

$$
V=(\mathbb{Z} / 3 \mathbb{Z})^{3}
$$

$$
\begin{aligned}
W & =\left\{\left(x_{1}, x_{2}, x_{3}\right) \in V: x_{1}+x_{2}+x_{3}=0\right\} \\
& =\left\{\left(-x_{2}-x_{3}, x_{2}, x_{3}\right): x_{2}, x_{3} \in \mathbb{Z} / 3 \mathbb{Z}\right\}
\end{aligned}
$$

## Example

$$
V=(\mathbb{Z} / 3 \mathbb{Z})^{3}
$$

$$
\begin{aligned}
W & =\left\{\left(x_{1}, x_{2}, x_{3}\right) \in V: x_{1}+x_{2}+x_{3}=0\right\} \\
& =\left\{\left(-x_{2}-x_{3}, x_{2}, x_{3}\right): x_{2}, x_{3} \in \mathbb{Z} / 3 \mathbb{Z}\right\}
\end{aligned}
$$

$$
W=\{(0,0,0),(2,1,0),(1,2,0),(2,0,1),(1,1,1),(0,2,1),
$$

$$
(1,0,2),(0,1,2),(2,2,2)\}
$$

## Coordinates

Definition. Let $B=\left\langle v_{1}, \ldots, v_{n}\right\rangle$ be an ordered basis for $V$. Given $v \in V$, there are unique $a_{1}, \ldots, a_{n} \in F$ such that

$$
v=a_{1} v_{1}+\cdots+a_{n} v_{n}
$$

## Coordinates

Definition. Let $B=\left\langle v_{1}, \ldots, v_{n}\right\rangle$ be an ordered basis for $V$. Given $v \in V$, there are unique $a_{1}, \ldots, a_{n} \in F$ such that

$$
v=a_{1} v_{1}+\cdots+a_{n} v_{n}
$$

The coordinates of $v$ with respect to the basis $B$ are the components of the vector $\left(a_{1}, \ldots, a_{n}\right) \in F^{n}$. We write

$$
[v]_{B}=\left(a_{1}, \ldots, a_{n}\right) .
$$

